

SFT covers for actions of the first Grigorchuk group

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Abstract

We study symbolic dynamical representations of actions of the first Grigorchuk group \mathcal{G} , namely its action on the boundary of the infinite rooted binary tree, its representation in the topological full group of a minimal substitutive \mathbb{Z} -shift, and its representation as a minimal system of Schreier graphs. We show that the first system admits an SFT cover, and the latter two systems are conjugate to sofic subshifts on \mathcal{G} , but are not of finite type.

1 Introduction

1.1 Symbolic dynamics

Classical symbolic systems called subshifts are dynamical systems associated with actions of the infinite cyclic group \mathbb{Z} (or a semigroup of natural numbers \mathbb{N}). Such a dynamical system is given by a pair (\mathbb{Z}, Ω) where Ω is a closed subset of the space $A^{\mathbb{Z}}$ supplied with the product topology, where A is a finite set (called the alphabet) of cardinality > 1 , the group \mathbb{Z} acts on Ω by shifts and Ω is topologically closed and invariant with respect to this action. The word “subshift” addresses the fact that (\mathbb{Z}, Ω) is a subsystem of the full shift $(\mathbb{Z}, A^{\mathbb{Z}})$.

Among such systems a special role is played by subshifts of finite type (SFT), i.e. subshifts determined by a finite set of forbidden words (called also strings or patterns) that are not allowed to appear in two-sided sequences $\omega \in \Omega$. A larger class of subshifts are sofic systems, which are their factors (meaning images under a shift-commuting continuous map). They can also be defined as subshifts determined by a set of forbidden words which constitutes a regular language over A . (Regular languages are the simplest class of languages in the classical Chomsky hierarchy of formal languages [12].)

A class orthogonal (in the classical one-dimensional setting) to the sofic systems is that of minimal subshifts, i.e. subshifts such that the orbit of each point $\omega \in \Omega$ is dense in Ω . The so-called primitive substitutions over alphabet A (for instance the famous Thue-Morse substitution $0 \rightarrow 01, 1 \rightarrow 10$ is an example of a primitive substitution) give a rich source of examples, as well as the so called Toeplitz sequences determining Toeplitz systems [30]. One-dimensional sofic systems have plenty of periodic points whose orbits are finite and hence are not dense in Ω (assuming Ω is infinite). The set Ω is usually assumed to be infinite and without isolated points, and in this case Ω is homeomorphic to a

Cantor set. A comprehensive account on SFT and sofic systems can be found in [33] while minimal systems are nicely described in [32] for instance.

A long time ago it was observed that one can build a theory of subshifts associated with an arbitrary group (or semigroup) G . Usually it is assumed that G is infinite and countable or even finitely generated. In this case the “full” space of interest is $\Omega = A^G$ and the group G naturally acts by shift of coordinates given by the left (or right) multiplication. The system (G, A^G) is a full shift and any closed G -invariant subset $\Omega \subset A^G$ gives the subshift system (G, Ω) . See for example [39, 16, 10, 11] and references therein.

For such systems one also can define a notion of SFT, by declaring that some finite set of patterns is forbidden from appearing in configurations ω from Ω . One can also define sofic G -systems as factors of G -SFT (it seems there is no suitable alternative definition of them using the terminology of formal languages over the groups). Factoring again means that given two G -systems X and Y there is a continuous G -equivariant surjective map $f : X \rightarrow Y$. If f is a homeomorphism then the systems are said to be conjugate. It is customary in topological dynamics to study group actions up to the equivalence relation of conjugacy similarly like in group theory groups are studied up to isomorphism.

The first considerations of this type were given for the free abelian groups $\mathbb{Z}^n, n \geq 2$ and led to numerous results including Berger’s result [8] on existence of SFT for \mathbb{Z}^2 with an aperiodic (i.e. free) action, meaning the absence of fixed points for elements different from the identity. This was done through the construction of an aperiodic Wang type tiling of the plane. On these groups, contrary to \mathbb{Z} , subshifts of finite type (and thus in particular sofic shifts) can be minimal [37].

The question of which groups support an SFT where the shift action is free, also known as a strongly aperiodic SFT, is widely studied, but open. A result of Jeandel [31] shows that algorithmic properties (complexity of the word problem or WP) can prevent the existence of a strongly aperiodic SFT, and another result of Cohen [15] shows that the number of ends provides a geometric restriction. There is also a long list of individual groups and classes of groups where strongly aperiodic SFTs do exist, in particular the group $\mathcal{E} = G_\omega = \langle a, b, c, d \rangle$ constructed in [20] (and studied in [21] and many other papers, including the present one) was shown to admit a strongly aperiodic SFT in [4].

1.2 Effectively closed and totally non-free actions

For groups with nice algorithmic properties there is a sense to study effective actions on zero-dimensional compact metric spaces, first of all on a Cantor set. Roughly speaking, the action of a group G with decidable word problem on $X \subset A^{\mathbb{N}}$ is effective if X is an effectively closed subset and for every $g \in G$ and $x \in X$ the map $x \mapsto g(x)$ is computable (for a precise definition see Section 2).

Remark 1. *As a word of warning, we note that in the theory of group actions, “effective” is sometimes used to as a synonym for “faithful”, but in the present article, it is rather a synonym for “computable” (or “lightface”), and refers to effective descriptive set theory.*

Arguably, a more fine-grained problem than the construction of strongly aperiodic SFTs is then to understand which effective actions of a group admit SFT covers. Namely, the existence of a free SFT on the group G is trivially

equivalent to the existence of any dynamical G -system with a free action, which admits an SFT cover (because periods are preserved under factor maps). This is in fact a common way to produce strongly aperiodic SFTs on groups: One first finds strongly aperiodic effective subshifts on G , and then proves that some (or all) such subshifts are sofic. For many groups, in particular most of the groups studied in [4, 5] (including the group \mathcal{G}), no other technique is known. This technique of *simulation* is discussed in more detail in the following section.

It is well-known that subshifts are characterized among dynamical systems on zero-dimensional compact metrizable spaces by the dynamical property of expansivity [27, 36], so restricting to expansive zero-dimensional systems, the question is simply: which (effective) subshifts are sofic? (Our interest is mainly in the study of recursively presented groups, on which all sofic shifts are effective [1].)

This question is not well-understood even on abelian groups. For example, let $X \subset \{0, 1\}^{\mathbb{Z}^3}$ be the set of configurations $x \in \{0, 1\}^{\mathbb{Z}^3}$ such that all finite connected components of 1-symbols (in the Cayley graph under the standard generators) have odd cardinality. It is not known whether X is sofic [28, 3].

A wide class of interesting actions is given by groups generated by (asynchronous) finite automata (viewed as sequential machines) as described for instance in [26]. This includes Thompson's groups, the group \mathcal{G} studied in the present paper and many more. At the moment there is a splash of interest in the group actions on a Cantor set inspired by studies around groups of Thompson-Higman type, groups of branch type, ample (or topological full groups) etc. Usually such actions are effective and the Cantor set is realized as a closed subset of the product space A^G where G is infinite group or a semigroup, or as a boundary of a regular rooted (or unrooted) tree T .

A new phenomenon that appears with such group actions is that (the space of) stabilizers of points is an interesting object, and a group can have an interesting action by conjugacy on its space of subgroups. This action is of course of special interest, as it is intrinsic to the group.

An interesting related notion is the following, due to Vershik [40]: Consider a group action on a standard atomless measure space X by a countable group G . Suppose further that μ is a measure on X which is invariant under the action of G (or at least quasi-invariant, meaning $g\mu$ and μ have the same measure zero sets for all $g \in G$). Then we say the action is called *totally non-free* if the stabilizers of almost all points are distinct. We call an abstract group action *totally absolutely non-free* if the stabilizers of all points are distinct.

It is known that the natural action of the group \mathcal{G} on the boundary of the binary rooted tree, which we call $(\mathcal{G}, \mathcal{T})$, is totally non-free in both senses [24]. This action is uniquely ergodic, meaning there is a unique probability measure that is invariant under it. The action defined in [42] of \mathcal{G} on is marked Schreier graphs, which we call $(\mathcal{G}, \mathcal{V})$, is also totally absolutely non-free. This is somehow implicit in [42], but we give a proof in Lemma 7. Another example is Thompson's V , whose natural (defining) action on Cantor space is totally absolutely non-free. It admits a quasi-invariant measure, but no invariant probability measure.

It is an interesting question which groups admit faithful totally non-free or absolutely non-free actions, and for groups that do, it is of interest to try to understand the dynamics of such actions. One concrete problem is to understand whether they can be SFTs or at least admit SFT covers. Note that this problem is in some sense of a "complementary nature" to the more studied problem of

finding strongly aperiodic SFTs on groups – here we want the group structure to be completely visible in the stabilizers, while in the latter we want to avoid stabilizers completely.

1.3 Simulation

We now recall a general approach for attacking problems related to soficity, called simulation. A good setting for it is that G, H are groups, and $\phi : G \rightarrow H$ is an epimorphism. Then an H -system can be pulled back to G -systems by the trivial formula $g \blacktriangleright x = \phi(g) \blacktriangleright x$.

Hochman showed in [29] that for any effective \mathbb{Z} -system (meaning one that can be described algorithmically, see Section 2), its pullback in \mathbb{Z}^3 admits an SFT cover (in particular, the pullback of an effective subshift is sofic). This result was improved (in the expansive case) by Aubrun and Sablik [2], and Durand, Romashchenko and Shen [19] by showing that the two-dimensional version of Hochman’s result is true: every effective \mathbb{Z} -subshift is topologically conjugate to the $(\mathbb{Z} \times \{0\})$ -subaction of a sofic \mathbb{Z}^2 -subshift.

These results inspired the direction of studies that got the name *simulation*, with the idea that we simulate actions in a quotient group by SFTs (up to a dynamical projection) in a covering group. As part of this terminology, a group G with the property that every effective action of G is a factor of a G -SFT is said to be *self-simulable group*.

The class of self-simulable groups was shown in [5] to include plenty of non-amenable groups: direct products $F_m \times F_n$ of noncommutative free groups, the linear groups $\mathrm{SL}(n, \mathbb{Z})$ for sufficiently large n , Thompson’s group V and many more. On the other hand amenable groups (in particular \mathbb{Z}^d and \mathcal{G}) are not self-simulable, so for them covering using larger groups is necessary. One basic reason for this is the (topological) entropy theory developed for countable amenable groups: under factorization the entropy drops, and SFTs (and more generally subshifts) have finite entropy while any (recursively-presented) amenable group has an effective action on a compact set with infinite topological entropy, see e.g. [5].

Since Thompson’s group V is self-simulable, its natural action on $\{0, 1\}^\omega$ is sofic. For this, it suffices to show that the action is expansive and effective. The former is well-known, and the latter is immediate from the defining formula. This gives an example of a totally absolutely non-free sofic shift. However, this system does not preserve any non-trivial probability measure.

Since the group \mathcal{G} is not self-simulable, the question of soficity of specific actions arises. It turns out that simulation tools apply well to this group. Namely \mathcal{G} belongs to the class of branch groups [23, 6], and hence has large product groups as a finite-index subgroups. Our main tool in this work will be the following simulation theorem for product groups, due to Sebastián Barbieri [4], which he used in particular to show that \mathcal{G} admits a strongly aperiodic subshift of finite type.

Theorem 1 ([4]). *Let G, H, K be three finitely-generated infinite groups, and $\pi : G \times H \times K \rightarrow G$ the natural projection. Then the π -pullback of any expansive effective G -system admits an $G \times H \times K$ -SFT cover.*

1.4 Results

Now we are ready to state our results, which deal with the group \mathcal{G} , in detail.

As mentioned, \mathcal{G} acts in a natural way by automorphisms of the binary rooted tree T_2 , and hence on its boundary $\mathcal{T} = \partial T_2$ which can be identified with $\{0, 1\}^\omega$. The action on the boundary is by homeomorphisms (in fact by isometries for a suitable ultrametric on \mathcal{T}).

The group \mathcal{G} also acts in a natural way on a certain closed subset \mathcal{S} of $\{a, B, C, D\}^\mathbb{Z}$ defined by Vorobets in [41] (with slightly different choice of symbols), which is the minimal subshift associated with Lysenok’s substitution from [34], and which we recall in Section 3. Specifically, Matte Bon showed in [35] that \mathcal{G} embeds in the topological full group of the \mathbb{Z} -shift map $\sigma_{\mathcal{S}}$ of \mathcal{S} (another proof is given in [25]). We also give a self-contained derivation of the embedding into the topological full group in the present paper.

We prove the following theorem.

Theorem 2. *The system $(\mathcal{G}, \mathcal{S})$ from [35] is topologically conjugate to a proper sofic shift on the group \mathcal{G} .*

Recall that a sofic shift is a subshift which is a factor of a subshift of finite type, and a sofic shift is proper if it is not conjugate to a subshift of finite type. The properness, i.e. non-SFTness, of $(\mathcal{G}, \mathcal{S})$, is shown in Lemma 25, and soficity in Lemma 24.

Vorobets studied in [42] a “more efficient” cover for $(\mathcal{G}, \mathcal{T})$, namely an almost 1-to-1 cover which we will call $(\mathcal{G}, \mathcal{V})$. This is the same system as $(\mathcal{G}, \mathcal{S})$ except that it is considered up to mirror-symmetry of the integer line (his system is directly a system of marked Schreier graphs), and accordingly it is a 2-to-1 factor of $(\mathcal{G}, \mathcal{S})$ [25]. We show in Section 8 that the direct analog of Theorem 2 holds for the system $(\mathcal{G}, \mathcal{V})$. Indeed we can deduce it abstractly from the above theorem.

Theorem 3. *The system $(\mathcal{G}, \mathcal{V})$ from [42] is topologically conjugate to a proper sofic shift on the group \mathcal{G} .*

As $(\mathcal{G}, \mathcal{S})$ (or $(\mathcal{G}, \mathcal{V})$) covers $(\mathcal{G}, \mathcal{T})$, we also get the following corollary:

Corollary 1. *The system $(\mathcal{G}, \mathcal{T})$ admits an SFT cover.*

As discussed, our proofs are based on simulation theory. Thus, while our theorem is a nice demonstration of the power of this theory, the fact that the SFT covers come from a general construction does in practice imply that they are very complicated.

Question 1. *Are there “nice” SFT covers for the systems $(\mathcal{G}, \mathcal{S})$, $(\mathcal{G}, \mathcal{V})$ and $(\mathcal{G}, \mathcal{T})$? Are there ones with small fibers, e.g. finite-to-1 on a residual or full measure set?*

We mention that in the case of the lamplighter group $\mathbb{Z}_2 \wr \mathbb{Z}$, while its natural action on $\mathbb{Z}_2^\mathbb{Z}$ is not an SFT, it has a 9-to-1 cocycle extension which is an SFT [7, Proposition 5.14]. In the case of Thompson’s V , we do not even know whether the natural action itself is an SFT.

Theorem 3 provides a natural example of a sofic shift on a finitely-generated group, which is uniquely ergodic with nonatomic measure, and where the shift-action is totally absolutely non-free (see Lemma 7 for a proof of this property).

We are not aware of other such examples. It is an interesting question whether there are natural examples of totally non-free actions that are SFTs without any extension. (Of particular interest would be a uniquely ergodic action of an amenable group.)

Question 2. *Is there a natural example of an SFT on a finitely-generated group G , which is totally (absolutely) non-free?*

Finally, for completeness we mention that for very general reasons the system $(\mathcal{G}, \mathcal{T})$ has the so-called pseudo-orbit tracing property, see Section 9. Despite the fact that this property characterizes the subshifts of finite type among subshifts, as far as we can tell it cannot be used to prove Corollary 1.

Proposition 1. *The system $(\mathcal{G}, \mathcal{T})$ is pseudo-orbit tracing.*

1.5 Structure of the paper

The paper is organized as follows. After giving some preliminaries in Section 2, we introduce the standard actions of the group \mathcal{G} in Section 3. This section mainly proves the well-known result that $(\mathcal{G}, \mathcal{S})$ factors onto $(\mathcal{G}, \mathcal{T})$ (with small fibers). We have attempted to write the section as a self-contained “symbolic dynamical take” on the proof. In Section 4 we give two constructions on SFTs, namely that SFTs are in an appropriate sense closed under union and finite extensions.

In Section 5 we show that $(\mathcal{G}, \mathcal{S})$ is expansive, thus (topologically conjugate to) a subshift on the group \mathcal{G} . In Section 6 we apply the theorem of Barbieri to show that it is sofic. In Section 7 we explain why it is not a subshift of finite type. In Section 8, we show the same results for the system $(\mathcal{G}, \mathcal{V})$. These results are obtained fully abstractly from good properties of the covering map. In Section 9 we explain why $(\mathcal{G}, \mathcal{T})$ has the pseudo-orbit tracing property.

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2 Preliminaries

Here we specify terminology and notations used in this article.

An *alphabet* is a finite discrete set A . We write A^* for the set of all words over the alphabet, including the empty word. If u, v are words, we write $u \cdot v$ or simply uv for their concatenation, meaning product as elements of a free monoid. The length of a word $u \in A^*$ is the number of letters it is composed of, and is denoted $|u|$. The empty word is the unique word of length 0.

We index a word starting from 0, so $u = u_0u_1 \cdots u_{|u|-1}$. Numbers i thought of as positions in a word are called *indices*. If $u \in A^*$ and $v \in A^\omega$ (ω being the first infinite ordinal), then we write $u \cdot v$ or just uv for $x \in A^\omega$ where $x_i = u_i$ for $0 \leq i < |u|$ and $x_i = v_{i-|u|}$ otherwise. We say $u \in A^*$ is a *subword* of $v \in A^*$ if $v = wuw'$ for some words $w, w' \in A^*$.

Intervals are by default discrete, $[i, j] = \{i, i + 1, \dots, j - 1, j\}$. We have $\mathbb{N} = \{0, 1, 2, \dots\}$.

Groups act from left. We use G for a generic group, and always write the first Grigorchuk group as \mathcal{G} . If G is a discrete countable group, a G -system is a compact metrizable zero-dimensional topological space X where G acts by homeomorphisms through some $\alpha : G \times X \rightarrow X$. Lowercase calligraphic letters are used for actions. We also denote the action by $\blacktriangleright_\alpha$ or just \blacktriangleright when α is clear from context, i.e. $\alpha(g, x) = g \blacktriangleright_\alpha x = g \blacktriangleright x$. When \blacktriangleright is clear from context (and especially for shift maps), we also use the shorter form $gx = g \blacktriangleright x$.

Two G -systems are (*topologically*) *conjugate* if there is a homeomorphism between them that commutes with the actions, and the map is called a *conjugacy*. Up to conjugacy, G -systems are just closed G -invariant subsets $X \subset (\{0, 1\}^{\mathbb{N}})^G$ with action given by the shift formula $g \blacktriangleright x_h = x_{hg}$. Factor maps (resp. embeddings) are G -commuting surjective (resp. injective) continuous maps from one G -set onto (resp. into) another. A preimage in a factor map is called an *extension* or a *cover*.

An *effective* G -system is a G -system such that $X \subset \{0, 1\}^{\mathbb{N}}$ is effectively closed, and the relation $R = \{(x, g \blacktriangleright x) \mid x \in \{0, 1\}^{\mathbb{N}}\}$ is effectively closed in $(\{0, 1\}^{\mathbb{N}})^2$ for all $g \in G$. Recall that a subset of $\{0, 1\}^{\mathbb{N}}$ is effectively closed if we can recursively enumerate a sequence of words such that the union of the corresponding cylinders is the complement of the subset; and for a relation R , effectively closed means that we can enumerate a sequence of pairs of words $(u_i, v_i) \in (\{0, 1\}^*)^2$ such that $\bigcup_i [u_i] \times [v_i]$ gives the complement of R . The notion of an effective G -system is equivalent to saying that $X \subset \{0, 1\}^{\mathbb{N}}$ is effectively closed and for every $g \in G$, the map $(x, n) \mapsto (g \blacktriangleright x)_n$ can be computed by a Turing machine (depending on g), with x given as an oracle, and n as input.

An *effective* G -subshift is simply a subshift that happens to be effective as a G -system. For G a finitely-generated group with decidable word problem, it is very transparent what this means. The group G is in computable bijection with \mathbb{N} (by representing $g \in G$ first as the lexicographically minimal word over a generating set, and then bijecting such words with \mathbb{N}), and the group operations are computable functions on \mathbb{N} . In particular, we can see configurations in A^G as elements of $A^{\mathbb{N}}$, and the shift maps are easily seen to be computable. Finally, one may code the system to the binary alphabet $\{0, 1\}$ by replacing letters by binary words of a fixed length.

A *pattern* is a function $P : D \rightarrow A$ where $D \subset G$ is finite. We say a pattern P *appears in* $x \in A^G$ *at* g if $g \blacktriangleright x \in [P]$, where $[P] = \{y \in A^G \mid y|_D = P\}$ is the *cylinder* defined by P . We simply say it appears if it appears at g for some g . We say P appears in a set of configurations $X \subset A^G$ if it appears in some $x \in X$.

A G -subshift over alphabet A is a topologically closed and G -invariant subset of $X \subset A^G$, where G acts on A^G by $gx_h = x_{hg}$. Equivalently, X is defined by forbidden patterns, in the sense that for some patterns P_1, P_2, \dots , we have $X = \{x \in A^G \mid \forall i : P_i \text{ does not appear in } x\}$. A G -SFT is a G -subshift defined by finitely many forbidden patterns. A *sofic* G -shift is a subshift that is a factor of an SFT. A *proper sofic shift* is a sofic shift that is not conjugate to an SFT. Here, an *effective subshift* is one that is topologically conjugate to an effective system. When G is finitely-generated with decidable word problem, this is equivalent to the subshift being definable by a recursively enumerable list of forbidden patterns P_1, P_2, \dots .

Up to topological conjugacy, being a subshift is equivalent to being *expansive*, i.e. for some $\epsilon > 0$, $\forall x \neq y : \exists g \in G : d(gx, gy) > \epsilon$. It is well-known that the SFT property is characterized among subshifts by the so-called pseudo-orbit tracing property [13], which we recall next.

If $\delta > 0$ and $F \Subset G$ is finite, then a (δ, F) -pseudo-orbit for the system (G, X) is a map $z : G \rightarrow X$ satisfying $d(sz(g), z(sg)) < \delta$ for all $g \in G, s \in F$. A point $x \in X$ ϵ -traces (or ϵ -shadows) a pseudo-orbit z if $d(gx, z(g)) < \epsilon$ for all $g \in G$. We say (G, X) has the *pseudo-orbit tracing property* (a.k.a. the *shadowing property*) if for all $\epsilon > 0$, there exists $\delta > 0$ and $F \Subset G$ such that every (δ, F) -pseudo-orbit is ϵ -traced by some $x \in X$.

The following is classical [44, 13].

Lemma 1. *For any group G , a G -subshift has the pseudo-orbit tracing property if and only if it is an SFT.*

Being sofic has no known simple characterization on most groups, the exceptions being that

- it is understood well on \mathbb{Z} [33] where sofic shifts are given by labelings of bi-infinite paths in a finite directed graph, and
- on self-simulable groups [5] with decidable word problem, a subshift $X \subset A^G$ is sofic if and only if the shift action of G is effective (in the sense of being an effective G -subshift, as discussed above).

A subshift $X \subset A^G$ is *minimal* if it is nonempty and any subshift $Y \subset X$ is either X or empty. This is equivalent to the property that the orbit of every point is dense, i.e. every nonempty open set is visited by every orbit. Then in fact for all nonempty open sets U (in particular for all nonempty cylinder sets) there exists a finite set $S \Subset G$ such that for all $x \in X$, we have $gx \in U$ for some $g \in S$.

Here we study which systems admit an SFT cover. Such systems are sometimes called “finite type” in the literature, but this terminology can be confusing, since a subshift which is of finite type need not be a subshift of finite type. It would also make sense to call these systems “sofic”, but there is a possibility of confusion here as well, since “sofic system” often refers to a “sofic subshift” in the literature. Thus, if X has an SFT cover, we will simply call it *SFT covered*.

On $A^{\mathbb{Z}}$ we use the metric d where for $x \neq y$ we define $d(x, y) = \inf\{2^{-n} \mid n \in \mathbb{N}, x_{[-n, n]} \neq y_{[-n, n]}\}$.

Definition 1. *Let (G, X) be a group acting on a compact topological space X . The topological full group $[[G, X]]$ consists of homeomorphisms h such that there exists a partition of the space X into clopen sets A_1, \dots, A_k and group elements g_1, \dots, g_k such that $h|_{A_i} = g_i|_{A_i}$ for all i .*

The data above can be summarized into a single continuous function $\gamma : X \rightarrow G$: we consider our groups G to be discrete, so the image, being compact, is finite. Then $A_g = \gamma^{-1}(\{g\})$ forms the clopen partition as g ranges over G , and we define $h|_{A_g} = g|_{A_g}$. Such γ is called a *cocycle*.

We also use the notation of Vorobets [43] in the case of a \mathbb{Z} -subshift (σ, X) , where σ now denotes the left shift $\sigma(x)_i = x_{i+1}$ (which corresponds to the the

action of $-1 \in \mathbb{Z}$ with our general formula). If U is a clopen set such that $U \cap \sigma(U) = \emptyset$, we define a homeomorphism $\delta_U : X \rightarrow X$ by

$$\delta_U(x) = \begin{cases} \sigma(x) & \text{if } x \in U \\ \sigma^{-1}(x) & \text{if } x \in \sigma(U) \\ x & \text{otherwise.} \end{cases}$$

If a \mathbb{Z} -subshift (σ, X) , $X \subset A^{\mathbb{Z}}$ for finite alphabet A , is clear from context, and $u \in A^*$, $i \in \mathbb{Z}$, then we also use a notation for positioned cylinders $[u]_i = \{x \in X \mid x_{[i, i+|u|-1]} = u\}$. Such a set is a cylinder in the previous more general sense, so it is clopen. The *language* of a \mathbb{Z} -subshift X is the set of words $w \in A^*$ such that $[w]_0$ is nonempty. A \mathbb{Z} -subshift X is minimal if and only if for all words u in the language of X , there exists n such that all words of length n in the language of X contain u as a subword.

3 The group \mathcal{G} and its actions

We now give a self-contained construction of the systems $(\mathcal{G}, \mathcal{T})$, $(\mathcal{G}, \mathcal{S})$ and $(\mathcal{G}, \mathcal{V})$. The first is the “defining” action on a tree boundary, the second is the topological full group action first defined by Matte Bon in [35], and the third is Vorobets’ action on Schreier graphs from [42] (which we present slightly differently). These sit in a chain of factoring relations (as explained in [25])

$$(\mathcal{G}, \mathcal{S}) \xrightarrow{2:1} (\mathcal{G}, \mathcal{V}) \xrightarrow{3:1, \text{ almost } 1:1} (\mathcal{G}, \mathcal{T})$$

3.1 Action on (the boundary of) a tree

Write $\mathcal{T} = \{0, 1\}^{\omega}$. We interpret \mathcal{T} as the boundary ∂T_2 of a binary rooted tree T_2 , and with the product topology \mathcal{T} is homeomorphic to Cantor space.

The group \mathcal{G} is generated by homeomorphisms $a, b, c, d : \mathcal{T} \rightarrow \mathcal{T}$ defined as follows: The homeomorphism a acts by $a \blacktriangleright \alpha x = (1 - \alpha)x$, where $\alpha \in \{0, 1\}$, $x \in T$. The homeomorphism $g \in \{b, c, d\}$ acts on a dense set of points by

$$g \blacktriangleright 1^n 0 \alpha x = \begin{cases} 1^n 0 (1 - \alpha) x & \text{if } n \not\equiv v_g \pmod{3}, \\ 1^n 0 \alpha x & \text{otherwise.} \end{cases}$$

where $v_b = 2, v_c = 1, v_d = 0$, and $g \blacktriangleright 1^{\mathbb{N}} = 1^{\mathbb{N}}$ for $g \in \{b, c, d\}$. This extends naturally and uniquely to a continuous action on \mathcal{T} .

Definition 2. *We call this defining action the tree action, and (when not clear from context) denote it by \blacktriangleright_t .*

The system $(\blacktriangleright_t, \mathcal{G}, \mathcal{T})$ is of course a \mathcal{G} -system, i.e. a compact metrizable zero-dimensional space with a continuous action of \mathcal{G} . It is useful to also define an action on $\{0, 1\}^m$ by the analogous formula (i.e. the quotient action when we project to the first m coordinates), and we use the same name for it. Note that elements of $\{0, 1\}^m$ correspond to vertices of T_2 at height m , and the action is by tree automorphisms.

3.2 Action on a \mathbb{Z} -subshift

We next define another action which is more directly related to symbolic dynamics. Recall that the group \mathcal{G} is not finitely-presented, but can be given a natural infinite (EDTOL [14]) presentation

$$\mathcal{G} = \langle a, b, c, d : a^2, b^2, c^2, d^2, bcd, \kappa^n((ad)^4), \kappa^n((adacac)^4), n = 0, 1, 2, \dots \rangle$$

where $\kappa : a \rightarrow aca, b \rightarrow d, c \rightarrow b, d \rightarrow c$ is a substitution (= free monoid endomorphism), the application of iterates of which to the relators $(ad)^4$ and $(adacac)^4$ gives two infinite sequences of relators involved in the presentation. This presentation was found by I. Lysenok in [34], and it was shown in [22] to be minimal, i.e. none of the relators can be dropped without changing the group. The substitution κ generates from a the same fixed point as the primitive substitution $\tau(a) = \tau(d) = ac, \tau(b) = ad, \tau(c) = ab$. This is a minimal \mathbb{Z} -subshift.

We next represent \mathcal{G} by bijections on certain “starred words”, with the goal of proving that \mathcal{G} embeds in the topological full group of the substitutive subshift \mathcal{S} given by κ (or τ), first observed in [35]. (Our subshift uses upper case letters and a different permutation of b, c, d , than [35] does.)

Remark 2. *We give the construction in detail, mostly to be self-contained, but also since we need some details in the proofs of Lemma 25 and Lemma 18. Of these, only Lemma 18 is needed for what we consider the main part of the proof, namely that $(\mathcal{G}, \mathcal{S})$ is sofic.*

An a -Alternating Word, or AW for short, is a word w in $\{a, B, C, D\}^*$ (i.e. a finite-length, possibly empty, word over this cardinality-4 alphabet) such that in every subword $\alpha\beta$ of w with $\alpha, \beta \in \{a, B, C, D\}$ exactly one of α, β is equal to a , i.e.

$$(\alpha = a \vee \beta = a) \wedge (\alpha \neq a \vee \beta \neq a).$$

Equivalently w is an AW if every a (non- a) symbol is followed by a non- a (resp. a) symbol (unless we are at the end of the word), and vice versa. For example, aBa , a and the empty word are AW s, while $aBBa$ is not.

A Starred a -Alternating Word or SAW is a word w in $\{a, B, C, D, \star\}^n$ for arbitrary n , where exactly one \star appears, and after we remove it we obtain an AW . For example $\star, a\star B$ are SAW s, but $a\star a$ is not. Let W be the set of all SAW s. *Starrings* of an AW are the SAW s obtained by inserting the star-symbol anywhere in the AW , and the resulting index of the star is the *star position*. For an AW of length k , the possible star positions are $[0, k]$.

The star \star can be thought of as a movable “origin” (which later in the topological full group context will literally translate to an origin). Other common symbols used for such a purpose are the decimal dot and the symbol $|$.

Geometrically, a word like $w = aDa\star CaDa$ may be pictured as

$$\begin{array}{cccccccc} | & | & | & | & | & | & | & | \\ a & D & a & \star & C & a & D & a \end{array}$$

i.e. replacing letters as labeled intervals of length 1, where the \star is between two of the intervals (or at one of the ends).

Consider the free product $H = \mathbb{Z}_2 * \mathbb{Z}_2^2$ where the \mathbb{Z}_2 generator is again a and b, c, d are the nontrivial elements of \mathbb{Z}_2^2 . As per the definition of a free

product, specifying an action of H is the same as specifying an action of \mathbb{Z}_2 , and an action of \mathbb{Z}_2^2 , which can be entirely independent. Recall that every element $h \in H$ can be put in *freely reduced form*, meaning in the form $a^x \alpha_1 a \alpha_2 \cdots \alpha_k a^y$ where $\alpha_i \in \{b, c, d\}$ and $x, y \in \{0, 1\}$, by simply performing multiplications and reductions greedily. These freely reduced forms are in one to one correspondence to the AWs, but play a somewhat different role.

Then H acts on the set of SAWs W by what we call the *jump action*, denoted \blacktriangleright_j , which we now define. The idea is that the generator a will have the unique \star jump over any a adjacent to it if one is present in the sense that if the subword $a\star$ appears, it is rewritten into $\star a$ and vice versa. We write “if present” since of course it is possible that there is no a -symbol adjacent to \star . Similarly, b has it jump over any adjacent C, D if present (i.e. it similarly jumps over either of these symbols); c jumps over B, D ; d jumps over B, C .

In formulas, the definition is as follows, where $\alpha, \beta \in \{a, B, C, D\}$ and $u, v \in \{a, B, C, D\}^*$:

$$\begin{aligned} \alpha \blacktriangleright_j u\star\beta v &= u\beta\star v \quad \text{if } \beta \in S_\alpha, \\ \alpha \blacktriangleright_j u\beta\star v &= u\star\beta v \quad \text{if } \beta \in S_\alpha \\ \alpha \blacktriangleright_j u\star v &= u\star v \quad \text{if neither of the above formulas can be applied.} \end{aligned}$$

Here, $S_a = \{a\}, S_b = \{C, D\}, S_c = \{B, D\}, S_d = \{B, C\}$. Note that the first and second cases cannot overlap for SAWs.

It is easy to verify that a acts by an involution and $\langle b, c, d \rangle$ satisfy the identities of \mathbb{Z}_2^2 , so this is indeed a well-defined action of H . Of course, this is not an action of \mathcal{G} . For example, ab is (like all other elements) of finite order in \mathcal{G} , but $(ab)^n \blacktriangleright_j (aD)^n \star = \star (aD)^n$ for all n in the action of H .

Define a list of AWs inductively by $w_1 = a$, and in general $w_{n+1} = w_n \alpha w_n$ where

$$\alpha = \begin{cases} B & \text{if } n \equiv 0 \pmod{3} \\ D & \text{if } n \equiv 1 \pmod{3} \\ C & \text{if } n \equiv 2 \pmod{3} \end{cases} \quad (1)$$

Checking that these are AWs is an immediate induction. Note that $|w_n| = 2^n - 1$, thus the possible star positions of starrings of w_n are $[0, 2^n - 1]$.

For explicitness, we enumerate a few initial words from this list:

$$w_1 = a, w_2 = aDa, w_3 = aDaCaDa, w_4 = aDaCaDaBaDaCaDa, \dots$$

We illustrate the H -action of $dadaba$ on a starring of w_3 ;

$$\begin{aligned} dadaba \blacktriangleright_j aDa\star CaDa &= dadab \blacktriangleright_j aD\star aCaDa \\ &= dada \blacktriangleright_j a\star DaCaDa \\ &= dad \blacktriangleright_j \star aDaCaDa \\ &= da \blacktriangleright_j \star aDaCaDa \\ &= d \blacktriangleright_j a\star DaCaDa \\ &= a\star DaCaDa \end{aligned}$$

Geometrically, the \star jumps around as follows:

Here, the first equality holds because w_{n+1} begins with w_n . The second holds because $g \blacktriangleright_n j = g \blacktriangleright_{n+1} j$ holds, which in turn is true because $j, g \blacktriangleright_{n+1} j \in [0, 2^n - 1]$, and by the definition of ϕ_{n+1} . The third holds because ϕ_n is a conjugacy so $\phi_n(g \blacktriangleright_n j) = g \blacktriangleright_t \phi_n(j)$, and the last bit is not affected in the application $g \blacktriangleright_t \phi_n(j)1$ because it can only be affected if $\phi_n(j) = 1^{n-1}0$, and in this case only if $\alpha \in S_g$. But then we would have $g \blacktriangleright_{n+1} j = 2^n$, contradicting the assumption $g \blacktriangleright_{n+1} j \in [0, 2^n - 1]$. The fourth equality is by definition.

Next, suppose $j, g \blacktriangleright_{n+1} j \in [2^n, 2^{n+1} - 1]$. Then we have the exact same calculation, though it looks more complicated. We first calculate $g \blacktriangleright_{n+1} j$ in terms of the action on starrings of w_n . If $g \blacktriangleright_n F(j) = F(j) + k$ then $g \blacktriangleright_{n+1} j = j - k$, because w_n is a palindrome and because by assumption $j - k \in [2^n, 2^{n+1} - 1]$. This gives

$$\begin{aligned} g \blacktriangleright_{n+1} j &= j - k \\ &= j - (g \blacktriangleright_n F(j) - F(j)) \\ &= j + F(j) - g \blacktriangleright_n F(j) \\ &= 2^{n+1} - 1 - g \blacktriangleright_n F(j) \\ &= F(g \blacktriangleright_n F(j)) \end{aligned}$$

Thus,

$$\begin{aligned} \phi_{n+1}(g \blacktriangleright_{n+1} j) &= \phi_{n+1}(F(g \blacktriangleright_n F(j))) \\ &= \phi_n(g \blacktriangleright_n F(j))0 \\ &= (g \blacktriangleright_t \phi_n(F(j)))0 \\ &= g \blacktriangleright_t \phi_{n+1}(j) \end{aligned}$$

Here the first equality was calculated above. The second is because F is an involution and $F(g \blacktriangleright_n F(j)) \in [2^n, 2^{n+1} - 1]$ (which in turn holds because $g \blacktriangleright_n F(j) \in [0, 2^n - 1]$, which is clear). The third equality is what we showed in the previous case. The fourth is by the definition of ϕ_{n+1} for inputs $\geq 2^n - 1$, and the fact that $j, g \blacktriangleright_{n+1} j \in [2^n, 2^{n+1} - 1]$ implies that the tree action does not flip the final bit of $\phi_{n+1}(j)$.

Finally assume $j \in [0, 2^n - 1]$ and $g \blacktriangleright_{n+1} j \notin [0, 2^n - 1]$ (the case of $j \notin [0, 2^n - 1]$ and $g \blacktriangleright_{n+1} j \in [0, 2^n - 1]$ being symmetric). Then of course $j = 2^n - 1$ and $g \blacktriangleright_{n+1} j = 2^n$, and if $w_{n+1} = w_n \alpha w_n$, then $g \in \{b, c, d\}$ and $\alpha \in S_g$. Direct calculations give

$$\phi_{n+1}(g \blacktriangleright_{n+1} j) = \phi_n(F(2^n))0 = \phi_n(2^n - 1)0 = 1^{n-1}00$$

and

$$g \blacktriangleright_t \phi_{n+1}(j) = g \blacktriangleright_t \phi_n(j)1 = g \blacktriangleright_t 1^{n-1}01 = 1^{n-1}00$$

because the fact that $\alpha \in S_g$ implies the last equality here, by the definition of the tree action.

This concludes the proof. \square

We can now easily derive the usual topological full group action.

Definition 3. Let $\mathcal{S} \subset \{a, B, C, D\}^{\mathbb{Z}}$ be the smallest \mathbb{Z} -subshift whose language contains the words w_n .

Lemma 3. The subshift \mathcal{S} is well-defined, and the following are equivalent for a word u with $u \leq |w_n|$:

- u is in the language of \mathcal{S} ,
- u is a subword of some w_m ,
- u is a subword of w_{n+3} ,
- u is a subword of $w_n\alpha w_n$ for some $\alpha \in \{B, C, D\}$.

Proof. We claim that the set U of all subwords of the words w_n is extendable, meaning one can always find a word of the form uw_nv in U with $|u|, |v| > 0$. The properties of extendability and closure under taking subwords are U known to characterize languages of subshift, so this shows that \mathcal{S} is well-defined and that U is its language (because any subshift containing the words w_n would certainly also have all words of U in its language). In other words it shows that equality of the first two items. For extendability of U , it suffices to show that w_n itself is extendable within U , and this is clear because $w_{n+2} = w_n\alpha w_n\beta w_n\alpha w_n$ where $\alpha, \beta \in \{B, C, D\}$.

It is clear that the third item only describes words in U . To see that the fourth item also only describes words in U , observe that

$$w_{n+3} = w_n\alpha w_n\beta w_n\alpha w_n\gamma w_n\alpha w_n\beta w_n\alpha w_n \quad (2)$$

where α, β, γ are distinct.

Suppose now that $u \in U$ and u with $u \leq |w_n|$. The claim in the fourth item clearly holds, because we see from the inductive definition that all words w_k fit the regular expression $(w_n(B + C + D))^*w_n$, and all subwords of such words, which have length at most $|w_n|$, fit inside subword of the form $w_n\alpha w_n$ for some $\alpha \in \{B, C, D\}$. Finally, (2) shows that w_{n+3} already contains all these words. \square

The following is proved in [41].

Lemma 4. The subshift \mathcal{S} (under the shift action of \mathbb{Z}) is minimal and has no periodic points.

Proof. If u appears in \mathcal{S} , then it appears in some w_n by definition. As observed in the previous proof, all words in the language of \mathcal{S} are subwords of words in $(w_n\{B, C, D\})^*w_n$, thus any word of length $2|w_n| + 1$ contains the word u . For aperiodicity, if a minimal subshift has a p -periodic point, then all its points are easily seen to be p -periodic. But obviously if $|w_n| \geq p$, at most one of the words $w_n\alpha w_n$ can be p -periodic for $\alpha \in \{B, C, D\}$, and all of these words appear in the language. \square

Another way to see the previous lemma is to observe that \mathcal{S} can also be generated by a primitive substitution [43], as it is well-known that the subshift generated by a primitive substitution is minimal and has no periodic points. In [41] it is in turn deduced from the fact that this subshift is the shift orbit closure of a Toeplitz sequence.

Lemma 5. *The group \mathcal{G} embeds in the topological full group of (σ, \mathcal{S}) , with the action induced by the jump action \blacktriangleright_j on the set of SAWs W .*

Proof. To get the cocycles of the elements of \mathcal{G} , we simply mimic the jump action, and shift the origin as if it were the star. More precisely, the generator $\alpha \in \{a, b, c, d\} \subset H$ is precisely δ_{U_α} , where $U_a = [a]_0, U_b = [C]_0 \cup [D]_0, U_c = [B]_0 \cup [D]_0, U_d = [B]_0 \cup [C]_0$. It is trivial to check that this gives an action of H . We will also denote this new action by \blacktriangleright_j , i.e. for now we have a system $(\blacktriangleright_j, H, \mathcal{S})$.

Suppose now $w \in H$ is presented as a freely reduced word over the generators of H , let $\gamma_i : \mathcal{S} \rightarrow \mathbb{Z}$ be the cocycle of the element $w_{[i, |w|-1]} \in H$, and let k be large enough that $\gamma_i(\mathcal{S}) \subset [-k+1, k-1]$ for all $0 \leq i \leq |w|-1$. Then for all i , $w_{[i, |w|-1]} \blacktriangleright_j(x) = \sigma^\ell(x)$ for some $|\ell| < k$. From this, and the fact \mathcal{S} has no periodic points (Lemma 4), it follows by comparing the definitions of the two jump actions that for all $x \in \mathcal{S}$, if we let $u = x_{[-k, -1]}, v = x_{[0, k]}$, we have $w \blacktriangleright_j x = x \iff w \blacktriangleright_j u \star v = u \star v$. Namely, the movement of the origin in our topological full group action on \mathcal{S} exactly mimics the movement of the star in the jump action.

Thus, since the language of \mathcal{S} contains only subwords of words w_n for various n , \blacktriangleright_j is in fact a well-defined action of \mathcal{G} . Since the jump action of \mathcal{G} on the union of starrings of w_n over all n is clearly faithful (because for a fixed n this is conjugate to the tree action on $\{0, 1\}^n$) and they all appear in the language of \mathcal{S} , this is in fact a faithful representation of \mathcal{G} . \square

We define the *reversal* map $f : \mathcal{S} \rightarrow \mathcal{S}$ by $f(x)_i = x_{-1-i}$. This is clearly an involution, and it preserves \mathcal{S} , since the language of \mathcal{S} is obviously invariant under reversal of finite words by Lemma 3. The reversal f also has no fixed points, simply because for all $\alpha \in \{a, B, C, D\}$ the cylinder $[\alpha]_0$ is mapped by f onto $[\alpha]_{-1}$, and these cylinders are disjoint.

Lemma 6. *The system $(\blacktriangleright_j, \mathcal{G}, \mathcal{S})$ is an extension of $(\blacktriangleright_t, \mathcal{G}, \mathcal{T})$ by a factor map $\phi : \mathcal{S} \rightarrow \mathcal{T}$ which is 2-to-1 on a residual set, and 6-to-1 on a countable set of fibers. We also have $\phi \circ f = f \circ \phi$.*

Proof. The definition of ϕ in a sense arises directly as an inverse limit of the maps ϕ_n . Let $x \in \mathcal{S}$ be arbitrary, and $n \geq 1$. Then by definition of \mathcal{S} , x is of the form

$$\dots w_n \beta_{-1} w_n \beta_0 w_n \beta_1 w_n \beta_2 \dots$$

for some symbols $\beta_i \in \{B, C, D\}$. We show by induction on n that for each $x \in V$, this choice of n th level decomposition is unique. This is obvious for $n = 1$ as $w_1 = a$. For $n > 1$, we first use the inductive hypothesis to find that there is a unique decomposition

$$\dots w_{n-1} \beta_{-1} w_{n-1} \beta_0 w_{n-1} \beta_1 w_{n-1} \beta_2 \dots$$

Any decomposition on level n will give a decomposition on level $n-1$, so we only have two choices left for the n th level decomposition.

By definition of \mathcal{S} , if $w_n = w_{n-1} \alpha w_{n-1}$, one of the period-2 subsequences of β_i is all- α . Say the one containing β_1 is, so we can write the decomposition of x above as

$$\dots (w_{n-1} \alpha w_{n-1}) \beta_{-2} (w_{n-1} \alpha w_{n-1}) \beta_0 (w_{n-1} \alpha w_{n-1}) \beta_2 (w_{n-1} \alpha w_{n-1}) \dots$$

If it were possible to find such x where an arbitrarily long subsequence of b_{2^i} is also all- α , we would find the periodic point $(w_{n-1}\alpha)^{\mathbb{Z}}$ in \mathcal{S} . But this is contradicted by the fact \mathcal{S} has no aperiodic points.

We call the w_n that appear in the decomposition the *natural* w_n s. From the uniqueness, it is automatic that the set of points x where a natural w_n appears in the coordinates $[0, 2^n - 1]$ is clopen, and its shifts partition the space into 2^n clopen sets.

For $x \in \mathcal{S}$, consider now the unique decomposition on level n . For any $n \geq 1$, the origin is next to, or inside, a unique natural w_{n+1} , in the sense that the leftmost coordinate of the interval where this w_{n+1} appears is in $(-\infty, 0]$, and the rightmost is in $[-1, \infty)$ (this is according to the convention that the origin is considered to be to the left of the position it is “at”). We call this unique w_{n+1} the *central* w_{n+1} . Say the central w_{n+1} occupies $[i, i + 2^{n+1} - 2]$, where then $i \in [-2^{n+1} + 1, 0]$. Then define

$$\psi_n(x) = \phi_{n+1}(-i)_{[0, n-1]}.$$

We want to show that $\psi_{n+1}(x)_{[0, n-1]} = \psi_n(x)_{[0, n-1]}$ for all n , and that each ψ is a factor map to the finite system $(\mathcal{t}, \mathcal{G}, \{0, 1\}^n)$, as then $\phi(x)_{[0, n-1]} = \psi_n(x)$ defines an equivariant map from $(\mathcal{G}, \mathcal{S})$ to $(\mathcal{G}, \mathcal{T})$.

The gist of the proof is that in the construction of the sequence of values $\phi_{n+1}(0), \dots, \phi_{n+1}(2^{n+1} - 1)$, the words in the first n bits follow first the sequence $\phi_n(0), \dots, \phi_n(2^n - 1)$ and then the inverse of it, so the sequence $\phi_{n+1}(0)_{[0, n-1]}, \dots, \phi_{n+1}(2^{n+1} - 1)_{[0, n-1]}$ is a palindrome. Now, in the construction of ϕ_{n+1+i} for $i \geq 1$ we will simply keep repeating this palindrome, since for a palindrome w we have the equality $ww^R = ww$.

Let us explain this in more detail. Suppose that the central w_{n+1} is in $[i, i + 2^{n+1} - 2]$. There are two possible intervals where the central w_{n+2} may appear, namely it may appear to the right (in $[i, i + 2^{n+2} - 2]$) or to the left (in $[i - 2^{n+1}, i + 2^{n+1} - 2]$) of the central w_{n+1} . First suppose the central w_{n+2} is in $[i, i + 2^{n+2} - 2]$. Then in the relative coordinates of the central w_{n+2} , the star position $j = -i$ (corresponding to the origin) is in the first half $[0, 2^{n+1} - 1]$. By the definition of ϕ_{n+2} , we then have $\phi_{n+2}(j) = \phi_{n+1}(j)1$, and the definitions agree.

If on the other hand the central w_{n+2} is to the left (in $[i - 2^{n+1}, i + 2^{n+1} - 2]$), then the position corresponding to the origin in the central w_{n+2} is $j = 2^{n+1} - i$, which is on the right half (since i is nonpositive). By the definition of ϕ_{n+2} , we then have $\phi_{n+2}(j) = \phi_{n+1}(F_{n+2}(j))0$, where $F_{n+2}(j) = 2^{n+2} - 1 - j$. We have

$$F_{n+2}(j) = 2^{n+2} - 1 - j = 2^{n+1} - 1 + i = F_{n+1}(-i),$$

so $\phi_{n+2}(j) = \phi_{n+1}(F_{n+1}(-i))0$.

Using the level $n + 1$ decomposition we would use instead the value of $\phi_{n+1}(-i)$ (like in the previous paragraph). Thus, it finally suffices to show that the first n coordinates of $\phi_{n+1}(j)$ and $\phi_{n+1}(F_{n+1}(j))$ agree for all $j \in [0, 2^n - 1]$. This is indeed immediate from the recursive definition of ϕ_{n+1} .

So far, we have shown that the map $\phi : \mathcal{S} \rightarrow \mathcal{T}$ is well-defined. Continuity is clear from the definition. For equivariance, we observe that for large enough t , the map ψ_n must behave equivariantly on $U_m = \bigcup_{\ell=t}^{m-t} [w_m]_{-\ell}$ for any m , because on the configurations where the word w_m defining the cylinder is indeed the central w_m (there are also configurations in $[w_m]_{-\ell}$ where the central w_m

is elsewhere), we simply mimic the action on starrings of w_m and thus the ψ_n -image must follow the conjugacy ϕ_n . The union of the U_m is easily seen to be dense, so ψ_n must be equivariant everywhere by continuity. As ϕ is just the inverse limit of these ϕ_n , it is equivariant. Now for surjectivity, it suffices to observe that $(\mathcal{G}, \mathcal{T})$ is minimal, which is obvious from Lemma 2.

Finally, we study the cardinality of fibers. It is easy to see that $\phi(f(x)) = \phi(x)$, since when reversing the configuration, we reflect the central w_{n+1} , which, as discussed above, immediately by the recursive definition of ϕ_{n+1} , preserves the first n bits. On the other hand, if we know all bits of $\phi(x)$, we know the positions of all the natural w_n s up to reversal. If this determines the point in \mathcal{S} up to reversal, the fiber has cardinality 2 as claimed, as the action of f is free.

Suppose then that the point is not determined up to reversal. This means that at least one position is not inside a natural w_n for any n . By shifting, we may assume this position is the origin. Up to reversal, we may assume the central w_n s are always to the left. Then the central w_n s are nested, and in fact we have

$$x_{[0, \infty)} = \alpha \lim_n w_n,$$

$$x_{(-\infty, -1]} = \lim_n w_n.$$

for some $\alpha \in \{B, C, D\}$, where the limits are taken in the obvious sense (to the right, and to the left, respectively). By Lemma 3, each of the three cases can occur for α , and this then gives the 6-to-1 orbits. \square

3.3 Action on Schreier graphs

The system studied by Vorobets in [42] is essentially the same as $(\mathcal{G}, \mathcal{S})$, except that we do not keep track of the orientation of the line (Vorobets studies this in the setting of marked Schreier graphs).

Definition 4. *Let $f : \mathcal{S} \rightarrow \mathcal{S}$ be the reversal map $f(x)_i = x_{-1-i}$. Then we define $\mathcal{V} = \mathcal{S}/f$ as the topological quotient $\{\{x, f(x)\} \mid x \in \mathcal{S}\}$, and \mathcal{G} acts on \mathcal{V} by $g \blacktriangleright \{x, f(x)\} = \{g \blacktriangleright_j x, g \blacktriangleright_j f(x)\}$.*

Note that $g \blacktriangleright_j f(x) = f(g \blacktriangleright_j x)$ by a direct computation (the definition of the jump action is obviously reversal-symmetric), so $\{g \blacktriangleright_j x, g \blacktriangleright_j f(x)\} = \{g \blacktriangleright_j x, f(g \blacktriangleright_j x)\} \in \mathcal{V}$ and \mathcal{V} is indeed closed under the action.

Lemma 7. *The system $(\blacktriangleright, \mathcal{G}, \mathcal{V})$ is totally absolutely non-free.*

Proof. Let $x \in \mathcal{S}$ be arbitrary. We claim that the symbols in x can be uniquely deduced from its stabilizer under the action of \blacktriangleright_j , up to reversal. To see this, observe that up to reversal we may assume $x_{-1} = a$. Then the symbol x_0 at the origin can be deduced from the information of which of the generators b, c, d fix x . Then we can inductively apply this procedure to $a \blacktriangleright_j x$ and any nontrivial shift $b \blacktriangleright_j x, c \blacktriangleright_j x, d \blacktriangleright_j x$, as from the stabilizer H of x , we also know the stabilizer gHg^{-1} of $g \blacktriangleright_j x$. Since $\mathcal{V} = \mathcal{S}/f$, we have shown that the point $\{x, f(x)\} \in \mathcal{V}$ is determined by its stabilizer. \square

The following is roughly (part of) the Factor Theorem of [25], and we only sketch the proof. See [42] for the definition of the space of marked Schreier graphs.

Lemma 8. *The system $(\mathcal{G}, \mathcal{V})$ is topologically conjugate to the system of Schreier graphs studied in [42].*

Proof. Recall that Vorobets' system in [42] is obtained from computing the Schreier graph of 1^ω under the tree action, computing the system of marked Schreier graphs generated by it, and finally removing the markings of the original Schreier graph (which are isolated points).

The map that takes $x \in \mathcal{S}$ to its Schreier graph is easily seen to be continuous. By the previous lemma, this map has kernel pair precisely $\{\{x, f(x)\} \mid x \in \mathcal{S}\}$. In the setting of compact Hausdorff spaces, continuous surjections are quotient maps, and two quotients with the same kernel pair are homeomorphic, so \mathcal{V}/f is indeed a system of Schreier graphs.

Since both systems are minimal, and both contain points that are arbitrarily good approximations of finite marked Schreier graphs arising from the SAWs $w_n \star \alpha w_n$, they must be the same system of marked Schreier graphs. \square

4 Basic constructions on SFTs

4.1 The union lemma

In this section, we show that class of SFTs is closed under disjoint union on finitely-generated groups. This is well-known at least on the groups \mathbb{Z}^d (see for example [33, Proposition 3.4.1] for \mathbb{Z}), and the proof for a general group differs mostly in notation.

We note that if P_1, \dots, P_n are the forbidden patterns defining an SFT, we may assume all the P_i have the same domain D , more generally we can always extend the domain of a forbidden pattern without changing the set of configurations it forbids, simply by replacing it by all its possible extensions over the alphabet.

Lemma 9. *Let $X_1, \dots, X_k \subset A^G$ be disjoint SFTs, and suppose G is finitely generated. Then the finite union $X = \bigcup_i X_i$ is an SFT.*

Proof. Subshifts are closed sets in A^G because they are defined by forbidding open sets (namely sets of the form $g^{-1}[P]$). Thus they are compact, and by basic topology there exists $\epsilon > 0$ such that the distance between any $x \in X_i$ and $y \in X_j$ is at least ϵ whenever $i \neq j$. By the definition of the product topology of A^G , and the compatibility of the metric with it, there exists a finite set $D \subset G$ such that $d(x, y) \geq \epsilon \implies x|_D \neq y|_D$. By possibly increasing D , we may assume that all the SFTs X_i admit defining sets of forbidden patterns with shape D . List the forbidden patterns of X_i as $P_{i,1}, \dots, P_{i,k_i} : D \rightarrow A$.

We give a set of forbidden patterns for an SFT Y , and then show that $Y = X$. Let $S \subset G$ be a finite generating set. The alphabet of Y is taken to be A . As for forbidden patterns, first in Y we forbid each pattern $P : D \rightarrow A$ such that P does not appear in any of the X_i . Then for each $s \in S$, we forbid the pattern $P : D \cup Ds \rightarrow A$ if for some $i \neq j$, we have

$$\exists x \in X_i : x|_D = P|_D \wedge \exists y \in X_j : y|_{Ds} = P|_{Ds}.$$

First let us show $X \subset Y$. Let $x \in X$; we show that none of the forbidden patterns appear in x at 1_G (this suffices because if one were to appear at g , then

it appears in gx at 1_G , and $gx \in X$ because X is shift-invariant as a union of shift-invariant sets). We have $x \in X_i$ for some i . By definition, $x|_D$ appears in X_i , so it is not in the first set of forbidden patterns.

Consider then the second family of forbidden patterns, i.e. pick some $s \in S$, and one of the forbidden patterns $P : D \cup Ds \rightarrow A$. Suppose that the SFTs from where the D - and Ds -patterns are taken have distinct indices i', j , i.e. $\exists x' \in X_{i'} : x'|_D = P|_D$ and $\exists y \in X_j : y|_{Ds} = P|_{Ds}$. Suppose now that P appears in x at 1_G . Since $d(x, y) > \epsilon$ for any point of $y \in X_k$ with $k \neq i$, and $x|_D = P|_D$, we must actually have $i' = i$, as the D -shaped pattern $P|_D$ appears in both $X_{i'}$ and X_i .

The assumption that $x|_{D \cup Ds} = P$ now implies $\exists y \in X_j : y|_{Ds} = x|_{Ds}$. But now $sx \in X_i$ and $sy \in X_j$ since SFTs are shift-invariant. For $d \in D$ we have $sy_d = y_{ds}$ and $sx_d = x_{ds}$ so $sx|_D = sy|_D$, again contradicting the fact that no D -shaped pattern appears in both X_i and X_j for $i \neq j$. We conclude that P cannot appear in x . This concludes the proof that $X \subset Y$.

Now let us prove $Y \subset X$. Suppose $y \in Y$. Then y avoids the first set of forbidden patterns so for some i we have $y|_D = x|_D$ for some $x \in X_i$. We claim that then for all $g \in G$ we have that $gy|_D$ appears in X_i . It suffices to show this for generators, i.e. whenever $y|_D$ appears in X_i , so does $sy|_D$, for $s \in S$. Suppose this fails, and for some $y \in Y$, we have that $y|_D$ appears in X_i but $sy|_D$ does not. We have $sy \in Y$ because Y is an SFT, and thus because sy avoids the first set of forbidden patterns we have that $sy|_D$ appears in some $z \in X_j$. This means that for all $d \in D$,

$$y_{ds} = sy_d = z_d = s^{-1}z_{ds},$$

so $y|_{Ds} = s^{-1}z|_{Ds}$. Note that $s^{-1}z \in X_j$ by shift-invariance of X_j .

Define $P = y|_{D \cup Ds}$. Now $y|_D$ appears in X_i , and $P|_{Ds} = y|_{Ds} = s^{-1}z|_{Ds}$ appears in X_j , so P is one of our forbidden patterns. This contradicts the assumption on y . We conclude that indeed if $y \in Y$ and $y|_D$ appears in X_i , then the same is true for all shifts of y .

But this means that whenever $y|_D$ appears in X_i , actually $y \in X_i$, because if $gy|_D$ always appears in a configuration of X_i , in particular it is not a forbidden pattern for X_i . We conclude that every configuration $y \in Y$ belongs to one of the X_i , thus $Y \subset X$. \square

Remark 3. *If the effective alphabets (the sets of symbols that actually appear in configurations) $A_i \subset A$ of the X_i are disjoint, the proof is simplified a bit, as we don't need to use the large shapes $D \cup Ds$ but can simply require each configuration to be over a single alphabet with patterns of shapes $\{1_G, s\}$. In fact, we can get an alternative proof of the above lemma from this, by taking a "higher block presentation" for each X_i by having each node remember the pattern around it. A higher block presentation is clearly a topological conjugacy, and SFTs are closed under topological conjugacy, so the union turns into a symbol-disjoint union. Finally you can recode it back, by dropping the extra information in each node, and we get that the union is SFT.*

Remark 4. *The above lemma is sharp in the sense that if G is not finitely-generated, then the union of finitely many (at least two) disjoint SFTs is never an SFT. This can be proved analogously to [38, Lemma 1], replacing 0- and 1-patches by patterns from two of the disjoint SFTs.*

Lemma 10. *A finite (not necessarily disjoint) union of sofic shifts on a finitely generated group G is sofic. More generally, for finitely generated G , a finite union of (not necessarily disjoint) SFT covered G -systems is SFT covered.*

Proof. Suppose X_1, \dots, X_k are systems with SFT covers $\phi_i : Y_i \rightarrow X_i$. We may assume the alphabets of the Y_i are disjoint. Then $Y = \bigsqcup_i Y_i$ is SFT, and the map $\phi : Y \rightarrow \bigcup_i X_i$ defined by $\phi(y) = \phi_i(y)$ for $y \in Y_i$ is clearly shift-invariant, continuous and surjective. This implies the “more generally” claim. In the sofic case, we simply observe that the union of the X_i is a subshift.² \square

4.2 The finite-index lemma

We now show that the existence of SFT covers is preserved under finite group extensions, in a rather general sense. We are not aware of a reference for such a result, but closely related commensurability-closure results can be found in the literature, see e.g. [18, Proposition 1] or [5, Lemma 7.2].

Lemma 11. *Let G be a finitely-generated group and let $(\blacktriangleright, G, X)$ be an arbitrary zero-dimensional system. Suppose H is a finite-index subgroup of G , and let $X' \subset X$ be an H -invariant subset (i.e. the restriction $(\blacktriangleright, H, X')$ is well-defined), and $G \blacktriangleright X' = X$. Suppose the subaction $(\blacktriangleright, H, X')$ admits an SFT cover. Then $(\blacktriangleright, G, X)$ admits an SFT cover.*

In our application we will have $X' = X$.

Proof. Pick coset representatives $R \subset G$ for H , i.e. $G = RH$. We may assume $1_G \in R$. Let $Y \subset W^H$ be an SFT cover for (H, X') , let $\phi : Y \rightarrow X'$ be the covering map. We may suppose this is given by Wang tiles, so we have a generating set S for H , $W \subset C^{S^\pm}$ (for each $s \in S$, including involutions, we have separate positive and negative copies s^+ and s^-) and the SFT rule is the color-matching rule: $x \in Y$ if and only if for all $g \in H$, the pair (x_g, x_{sg}) satisfies the s -color-matching rule $(x_g)_{s^+} = (x_{sg})_{s^-}$.

We take as the new alphabet $Q = \{\perp\} \cup W$ and define an SFT $Z \subset Q^G$ as follows: The first SFT rule is that for each $s \in S$, we require that if $x_g \in W$, then $x_{sg} \in W$, and the pair (x_g, x_{sg}) satisfies the s -color-matching rule. The second SFT rule is that if $x_g \in W$, then $x_{rg} = \perp$ for all $r \in R \setminus \{1_G\}$. Finally, require that for each $g \in G$, at least one symbol in $x|_{R^{-1}g}$ is in W . These three rules define an SFT Z .

We claim that Z is nonempty. Indeed, if $y \in Y$ then define $x = f(y) \in Q^G$ by $x|_H = y$, and $x_g = \perp$ otherwise. Then the first rule is obviously satisfied. The second is satisfied because R is a set of coset representatives for H , so

$$x_g \in W \implies g \in H \implies x_{rg} \notin H \implies x_{rg} = \perp$$

for $r \in R \setminus \{1_G\}$. Finally, the third rule is satisfied because if $g \in G$ then $g = rh$ for some $r \in R$, $h \in H$, and then $r^{-1}g = h \in H \implies x_{r^{-1}g} \in W$.

If $x \in Z$ and $x_{1_G} \in W$, then it is easy to see that we have $\{g \in G \mid x_g \in W\} = H$, namely the set on the left contains H by the first SFT rule, and since $G = RH$ the second rule forces $x_g = \perp$ for $g \notin H$. Consider now a general

²Note that in general, the union of two expansive subsystems of a fixed system is *not* expansive, here instead we are saying that the union is a subsystem of an expansive system (the full shift), and every subsystem of an expansive system is expansive.

$z \in Z$. By the third rule, at least one symbol in z is in W , indeed there exists $r \in R$ such that $r^{-1}z_{1_G} \in W$. Since $x = r^{-1}z$ satisfies $x_{1_G} \in W$, by the first observation of this paragraph we have $\{g \in G \mid x_g \in W\} = H$, and then for $rx = z$ we have $\{g \in G \mid z_g \in W\} = Hr^{-1}$. Since R^{-1} is a set of right coset representatives, we conclude that for any $z \in Z$, there in fact exists a unique $r \in R$ such that $r^{-1}z|_{1_G} \in W$. We say $r \in R$ is the *phase* of z .

Next, we describe a function $\psi : Z \rightarrow X$. Let $x \in Z$. If $x_{1_G} \in W$, i.e. the phase is 1_G , then by the first SFT rule the configuration $x|_H \in W^H$ is in Y , and we define $\psi(x) = \phi(x|_H) \in X$ in this case (the image is in X' but we see it as an element of X). If the phase is $r \in R \setminus \{1_G\}$ meaning $(r^{-1}x)|_H \in Y$ then we define $\psi(x) = r \blacktriangleright \phi((r^{-1}x)|_H)$.

It is obvious that ψ is continuous, because it is defined piecewise on $|R|$ many disjoint clopen sets, and on the clopen set corresponding to $r \in R$ it is defined by the formula $\psi(x) = r \blacktriangleright \phi((r^{-1}x)|_H)$, which is a composition of finitely many continuous functions. Namely, the outer action $y \mapsto r \blacktriangleright y$ was assumed continuous, the inner (shift) action $x \mapsto r^{-1}x$ is continuous, and $y \mapsto \phi(y|_H)$ is continuous by the assumption that ϕ is a factor map and restriction is continuous.

We claim that ψ is surjective onto X . To see this, let $x \in X$ be arbitrary. If $x \in X'$, pick $y \in Y$ a ϕ -preimage, and define a configuration $z = f(y) \in Z$ as above. Now by definition $\psi(z) = x$.

Next, suppose $x \notin X'$. By the assumption $G \blacktriangleright X' = X$, we have $x = g \blacktriangleright x'$ for some $g \in G, x' \in X'$, and because $H \blacktriangleright X' = X'$, we may assume $r \blacktriangleright x' = x$ for $r \in R$ (up to possibly changing x'). Let $\phi(y) = x'$ and again take $z = f(y)$ so $\psi(z) = x'$. Now consider the point $z' = rz$. Clearly its phase is r , since $z_{1_G} \in W$. Thus

$$\psi(z') = r \blacktriangleright \phi((r^{-1}z')|_H) = r \blacktriangleright \phi(z)|_H = r \blacktriangleright x' = x.$$

Next, we claim that ψ intertwines the shift map and the action of G i.e. $\psi(gz) = g \blacktriangleright \psi(z)$ for all $z \in Z, g \in G$. Suppose $\psi(z) = x$ and let $g \in G$. The idea is to go from z to gz by adding an artificial shift step changing the phase to 1_G . The idea is that we visualize a configuration as a “comb” having its W -symbols on a “spine” of shape Hr^{-1} , and other $g \in G$ on the “teeth” reached from the spine by moving by elements of R on the left. For movement on the spine, the fact the actions are conjugated is obvious, and the definition of ψ outside the spine is explicitly the desired conjugation formula.

We now translate the idea into formulas. First, to move along teeth to the spine, suppose $z \in Z$ has phase r , and $g = r^{-1}$. Then in fact the definition of ψ gives directly $\psi(z) = r \blacktriangleright \phi(gz)$ meaning $g \blacktriangleright \psi(z) = \phi(gz) = \psi(gz)$ (since gz has phase 1 so $\phi(gz) = \psi(gz)$). Moving from the spine up the teeth (i.e. the case that $z \in Z$ has phase 1 and $g \in R$) is given by a similar calculation. As for moving on the spine, suppose z and gz have phase 1_G . Then $g \in H$ and by definition of the shift map and the assumption that ϕ commutes with the H -actions, we have

$$g \blacktriangleright \psi(z) = g \blacktriangleright \phi(z|_H) = \phi(gz|_H) = \psi(gz).$$

In the general case, let $r \in R$ be the phase of z , and let r' be the phase of gz , so that $r^{-1}z|_H, r'^{-1}gz|_H \in Y$, i.e. z has W -symbols precisely in the set Hr^{-1} , and on the other hand precisely in the set $Hr'^{-1}g$ (recall that there is

a unique left coset containing W -symbols). We then have $Hr^{-1} = Hr'^{-1}g$ so $h = r'^{-1}gr \in H$, and we have $g = r'hr^{-1}$.

We first move to the spine:

$$\psi(r^{-1}z) = r^{-1} \blacktriangleright \psi(z).$$

Next, $r^{-1}z$ has phase 1_G and $r'^{-1}gr \in H$ so moving along the spine gives:

$$\psi(r'^{-1}gr \cdot r^{-1}z) = r'^{-1}gr \blacktriangleright \psi(r^{-1}z).$$

Next, $r'^{-1}gr \blacktriangleright r^{-1}z$ has phase 1_G (since translation by an H -element clearly preserves phase 1_G), so moving away from a spine gives:

$$\psi(r' \cdot r'^{-1}grr^{-1}z) = r' \blacktriangleright \psi(r'^{-1}grr^{-1}z).$$

All in all,

$$\begin{aligned} \psi(g \cdot z) &= \psi(r' \cdot r'^{-1}grr^{-1}z) \\ &= r' \blacktriangleright \psi(r'^{-1}gr \cdot r^{-1}z) \\ &= r' \blacktriangleright r'^{-1}gr \blacktriangleright \psi(r^{-1}z) \\ &= r' \blacktriangleright r'^{-1}gr \blacktriangleright r^{-1} \blacktriangleright \psi(z) \\ &= g \blacktriangleright \psi(z). \end{aligned}$$

□

5 The system $(\mathcal{G}, \mathcal{S})$ is a subshift

Lemma 12. *Let (G, X) be a compact zero-dimensional dynamical system. If the topological full group $[[G, X]]$ has a finitely-generated expansive subgroup, then (G, X) is expansive.*

Proof. Let $H = \langle h_1, \dots, h_k \rangle \leq [[G, X]]$ be expansive with constant $\epsilon > 0$, and suppose the generating set $\{h_i\}$ is symmetric. Since h_i is in the topological full group, there is a continuous cocycle $\gamma_i : X \rightarrow G$ for it, and since G is discrete, this only depends on a clopen partition of X , and $\gamma_i(X) = F_i \Subset G$ is finite. By possibly decreasing ϵ we may assume $d(x, y) < \epsilon \implies \forall i : \gamma_i(x) = \gamma_i(y)$.

Suppose now $x \neq y$. By expansivity of the subgroup H , there exists $h = h_{i_m} \cdots h_{i_2} h_{i_1} \in H$ such that we have $d(hx, hy) \geq \epsilon$.

Take a minimal possible m . By definition we have

$$hx = g_{i_m} \cdots g_{i_2} g_{i_1} x$$

where $g_{i_j} = \gamma_{i_j}(h_{i_{j-1}} \cdots h_{i_2} h_{i_1} x)$. By the assumption on ϵ and minimality of m , we also have $hy = g_{i_m} \cdots g_{i_2} g_{i_1} y$, thus $d(gx, gy) \geq \epsilon$ for $g = g_{i_m} \cdots g_{i_2} g_{i_1}$, proving expansivity. □

Lemma 13. *Let $(\blacktriangleright_{\mathcal{J}}, \mathcal{G}, \mathcal{S})$ be the group \mathcal{G} acting on \mathcal{S} by the jump action. Then $\sigma_{\mathcal{S}} \in [[\blacktriangleright_{\mathcal{J}}, \mathcal{G}, \mathcal{S}]]$, where $\sigma_{\mathcal{S}}$ is the shift map on \mathcal{S} defined by $\sigma_{\mathcal{S}}(x)_i = x_{i+1}$.*

Proof. Take the partition $A_1 = [a]_0$, $A_2 = [B]_0$, $A_3 = [C]_0$, $A_4 = [D]_0$, and $g_1 = a$, $g_2 = c$, $g_3 = d$, $g_4 = b$. This defines the shift map, because by the definition of the jump action on \mathcal{S} , g_i shifts points in $[A_i]_0$ one step to the left. \square

Lemma 14. *The system $(\mathcal{G}, \mathcal{S})$ is expansive, hence conjugate to a subshift over some finite alphabet.*

Proof. The space is clearly a Cantor set, so it suffices to show expansivity. By the previous lemma, $[(\mathcal{G}, \mathcal{S})]$ contains the finitely-generated subgroup $\langle \sigma_{\mathcal{S}} \rangle \cong \mathbb{Z}$, which already acts expansively. By Lemma 12, $(\mathcal{G}, \mathcal{S})$ is expansive. \square

Remark 5. *Note that $\sigma_{\mathcal{S}}$ is not itself the jump action of any element of the group \mathcal{G} , since \mathcal{G} is a torsion-free.*

6 The system $(\mathcal{G}, \mathcal{S})$ is a sofic subshift

In this section, we prove the first part of Theorem 2 (soficness). The second part (properness) is proved in the next section.

As discussed in the introduction, if $\pi : G \rightarrow H$ is a group homomorphism, for H -systems we can define their *pullback*, this is just the G -system with the same space and with action $g \blacktriangleright x = \pi(g) \blacktriangleright x$. The following theorem is due to Sebastián Barbieri [4].

Theorem 4. *Let G, H, K be three finitely-generated infinite groups, and $\pi : G \times H \times K \rightarrow G$ the natural projection. Then the π -pullback of any effective expansive G -system admits an $G \times H \times K$ -SFT cover.*

For $\alpha, \beta \in \{0, 1\}$ let $G_{\alpha\beta}$ be the subgroup of the group \mathcal{G} containing those $g \in \mathcal{G}$ satisfying:

$$\forall \alpha', \beta' \in \{0, 1\} : \alpha' \beta' \neq \alpha \beta \implies \forall x \in \{0, 1\}^{\mathbb{N}} : g \blacktriangleright_t \alpha' \beta' x = \alpha' \beta' x.$$

Of course for $g \in G_{\alpha\beta}$ we have

$$\forall x \in \{0, 1\}^{\mathbb{N}} : \exists y \in \{0, 1\}^{\mathbb{N}} : g \blacktriangleright_t \alpha \beta x = \alpha \beta y$$

The groups $G_{\alpha\beta}$ are usually called rigid stabilizers of the second level [23].

The following is well-known [17]:

Lemma 15. *The subgroup $\mathcal{G}_2 = G_{00} \times G_{01} \times G_{10} \times G_{11}$ is of finite index in \mathcal{G} .*

Let $\phi : \mathcal{S} \rightarrow \mathcal{T}$ be the map from Lemma 6. Consider the clopen set $\mathcal{T}_{\alpha\beta} = \alpha\beta\{0, 1\}^{\mathbb{N}}$ of words that begin with $\alpha\beta \in \{0, 1\}^2$, and observe that the subgroup $G_{\alpha\beta} \leq \mathcal{G}$ stabilizes $\mathcal{T}_{\alpha\beta}$ (as a set), while $G_{\alpha'\beta'}$ stabilizes it pointwise. Let now $\mathcal{S}_{\alpha\beta} = \phi^{-1}(\mathcal{T}_{\alpha\beta})$, another clopen set (since ϕ is continuous).

Lemma 16. *For all $\alpha\beta$, the action of \mathcal{G}_2 stabilizes $\mathcal{S}_{\alpha\beta}$ as a set.*

Proof. Clearly \mathcal{G}_2 stabilizes each $\mathcal{T}_{\alpha\beta}$ as a set. If $g \in \mathcal{G}_2$ and $x \in \mathcal{S}_{\alpha\beta}$, then $\phi(x) \in \mathcal{T}_{\alpha\beta}$ so $\phi(g \blacktriangleright_j x) = g \blacktriangleright_t \phi(x) \in g \blacktriangleright_t \mathcal{T}_{\alpha\beta} = \mathcal{T}_{\alpha\beta}$, thus $g \blacktriangleright_j x \in \phi^{-1}(\mathcal{T}_{\alpha\beta}) = \mathcal{S}_{\alpha\beta}$. \square

We obtain that $(\mathcal{G}_2, \mathcal{S})$ is a direct union of the corresponding subsystems.

Lemma 17. *The system $(\mathcal{G}_2, \mathcal{S})$ is a disjoint union $\bigsqcup_{\alpha, \beta} (\mathcal{G}_2, \mathcal{S}_{\alpha\beta})$.*

Since ϕ is a factor map, $G_{\alpha\beta}$ fixes fibers of points in $\mathcal{S}_{\alpha'\beta'}$ when $\alpha\beta \neq \alpha'\beta'$, but in principle it could move points within the fibers. We show that this action is trivial.

Lemma 18. *For all $\alpha\beta \neq \alpha'\beta'$, the action of $G_{\alpha\beta}$ stabilizes $\mathcal{S}_{\alpha'\beta'}$ pointwise.*

Proof. If not, then there is $g \in G_{\alpha\beta}$ that maps some $x \in \mathcal{S}_{\alpha'\beta'}$ into a different point in its fiber. Since the action of g is continuous and \mathcal{S} is a Cantor space, we may assume x is not in the countable set C of points with fiber size 6. Thus, g in fact acts as the reversal map f on the point x . In particular, g acts nontrivially on every point sufficiently close to x , and we conclude that g acts as precisely f on $U \setminus C$, where U is an open set containing x . Then it acts as f on all of U , since $U \setminus C$ is dense in U .

On the other hand, if U is small enough, then g acts as a fixed power of the shift in U , since the jump action is by elements of the topological full group. Thus it suffices to show that there cannot be any nonempty open set where σ^k acts as the reversal f .

To see that this is impossible, observe that any point $x \in \mathcal{S}$ in such an open set U would have a shift by some σ^m which is again in U (since $(\sigma_{\mathcal{S}}, \mathcal{S})$ is minimal), and the first shift σ^k would again give its reflection. Composing two distinct reflections gives a shift, so this would give us a periodic point.

In formulas, suppose $x \in U$. Then x satisfies $x_{i+k} = \sigma^k(x)_i = f(x)_i = x_{-1-i}$, for all i . Since $(\sigma_{\mathcal{S}}, \mathcal{S})$ is minimal, there exists a positive m such that $\sigma^m(x) \in U$, so that also $x_{i+k+m} = \sigma^{k+m}(x)_i = f(\sigma^m(x))_i = x_{-1-i+m}$, for all i . Then $x_{i+k} = x_{-1-i}$ and $x_{i+k+m} = x_{-1-i+m}$ for all i . Replacing i by $i+m$ in the second equality, we conclude $x_{i+k+2m} = x_{i+k}$ for all i , so x is periodic, contradicting the aperiodicity of \mathcal{S} . \square

Next, we have to prove expansivity of $(G_{\alpha\beta}, \mathcal{S}_{\alpha\beta})$, to be able to apply Theorem 4.

Lemma 19. *The system $(G_{\alpha\beta}, \mathcal{S}_{\alpha\beta})$ is expansive.*

Proof. The subgroup \mathcal{G}_2 is of finite index in \mathcal{G} , let $\mathcal{G} = S\mathcal{G}_2$ for a finite set S . The group \mathcal{G} acts expansively on \mathcal{S} by Lemma 14, so there exists $\epsilon > 0$ such that for any distinct $x, y \in \mathcal{S}_{\alpha\beta}$ there exists $g \in \mathcal{G}$ such that $d(gx, gy) > \epsilon$. Then for suitable $\delta > 0$, chosen using continuity of the actions of $s \in S$, we still have $d(sgx, sgy) > \delta$ where $s \in S$ is such that $sg \in \mathcal{G}_2$. Using the decomposition $\mathcal{G}_2 = G_{00} \times G_{01} \times G_{10} \times G_{11}$ we can write $sg = (g_{00}, g_{01}, g_{10}, g_{11})$. For $\alpha'\beta' \neq \alpha\beta$, the element $g_{\alpha'\beta'}$ fixes x and y (since it fixes $\mathcal{S}_{\alpha'\beta'}$ pointwise), thus $d(g_{\alpha\beta}x, g_{\alpha\beta}y) = d(sgx, sgy) > \delta$, showing expansivity. \square

Lemma 20. *For all $\alpha\beta$, the system $(\mathcal{G}_2, \mathcal{S}_{\alpha\beta})$ is the pullback of the system $(G_{\alpha\beta}, \mathcal{S}_{\alpha\beta})$ under the natural projection $\pi : \mathcal{G}_2 \rightarrow G_{\alpha\beta}$.*

Proof. Using the decomposition $\mathcal{G}_2 = G_{00} \times G_{01} \times G_{10} \times G_{11}$, if $x \in \mathcal{S}_{\alpha\beta}$ we have $(g_{00}, g_{01}, g_{10}, g_{11}) \blacktriangleright x = g_{\alpha\beta} \blacktriangleright x$, which is the definition of the pullback. \square

Lemma 21. *For any $\alpha, \beta \in \{0, 1\}$, the system $(G_{\alpha\beta}, \mathcal{S}_{\alpha\beta})$ is effective.*

Proof. We first show that the subset $\mathcal{S}_{\alpha\beta} \subset \{a, B, C, D\}^{\mathbb{Z}}$ is effectively closed (after bijecting \mathbb{Z} with \mathbb{N} by any computable formula). First we show that \mathcal{S} is, i.e. a set of forbidden patterns can be enumerated for it. First this, it suffices to give an algorithm for checking whether a given word u appears in the language of the subshift. But Lemma 3 immediately gives such an algorithm since it suffices to check whether u appears as a subword of w_{n+3} where $|u| \leq |w_n|$. We now observe that $\mathcal{S}_{\alpha\beta}$ is a clopen subset of \mathcal{S} , so it suffices to add a finite set of additional forbidden patterns to define it.

Next, we need to show that the actions of elements of $G_{\alpha\beta}$ are computable. Again, we start by showing that even the action of \mathcal{G} on \mathcal{S} is computable. This is immediate, as we defined the action by an explicit formula: For a generator $g \in \{a, b, c, d\}$, the action on a point $x \in \mathcal{S}$ is to look at the symbols in the immediate neighborhood of the origin $0 \in \mathbb{Z}$ in x , and then shift the entire configuration. This is conjugated to a computable permutation of \mathbb{N} through our choice of bijection $\mathbb{Z} \cong \mathbb{N}$ in the previous paragraph. Composition of computable functions is computable, and finally the restriction to $(G_{\alpha\beta}, \mathcal{S}_{\alpha\beta})$ preserves computability of the actions of all elements $g \in G_{\alpha\beta}$. \square

Lemma 22. *For all α, β , the system $(\mathcal{G}_2, \mathcal{S}_{\alpha\beta})$ is topologically conjugate to a sofic shift.*

Proof. Let $G = G_{\alpha\beta}, H = G_{(1-\alpha)\beta}, K = G_{(1-\alpha)(1-\beta)} \times G_{\alpha(1-\beta)}$. Then $(\mathcal{G}_2, \mathcal{S}_{\alpha\beta}) = (G \times H \times K, \mathcal{S}_{\alpha\beta})$ is the pullback of $(G, \mathcal{S}_{\alpha\beta})$ under the natural projection by Lemma 20. By Lemma 19, $(G, \mathcal{S}_{\alpha\beta})$ is expansive, and by the previous lemma, it is also effective. Thus, Theorem 4 implies that this system is SFT covered. \square

Lemma 23. *The system $(\mathcal{G}_2, \mathcal{S})$ is topologically conjugate to a sofic shift.*

Proof. By Lemma 17, $(\mathcal{G}_2, \mathcal{S}) \cong \bigsqcup_{\alpha, \beta} (\mathcal{G}_2, \mathcal{S}_{\alpha\beta})$. By Lemma 22 each $(\mathcal{G}_2, \mathcal{S}_{\alpha\beta})$ is sofic. By Lemma 10, $(\mathcal{G}_2, \mathcal{S})$ is sofic. \square

This is the first (and main) half of our main result:

Lemma 24. *The system $(\mathcal{G}, \mathcal{S})$ is topologically conjugate to a sofic shift.*

Proof. Set $G = \mathcal{G}, H = \mathcal{G}_2, X = X' = \mathcal{S}$. Then H is a finitely-generated finite-index subgroup of G , (G, X) is a zero-dimensional system, and $(H, X') = (\mathcal{G}_2, \mathcal{S})$ admits an SFT cover by the previous lemma. By Lemma 11, the system $(\mathcal{G}, \mathcal{S}) = (G, X)$ admits an SFT cover. By Lemma 14, it is a subshift, thus by definition it is sofic. \square

7 The system $(\mathcal{G}, \mathcal{S})$ is not an SFT

We now prove the second half of our main result, that $(\mathcal{G}, \mathcal{S})$ is not an SFT.

Lemma 25. *The system $(\mathcal{G}, \mathcal{S})$ is not conjugate to a subshift of finite type.*

Proof. The idea is to show that there are shift-periodic points in arbitrarily good SFT approximations of \mathcal{S} (meaning \mathbb{Z} -SFTs whose forbidden patterns are the words of length n that do not appear in the language of \mathcal{S}), such that \mathcal{G} still admits a well-defined action on their orbit. Then any set of points that locally look like these periodic points provides a pseudo-orbit that cannot be traced, since the action of \mathcal{G} on \mathcal{S} has no finite orbits and is expansive.

This is less trivial than it may appear. If \mathcal{G} were finitely presented, it would suffice to take any good enough SFT approximation so that all the relations are “visible”, and then the action of \mathcal{G} would be well-defined on this entire SFT – since \mathcal{S} is minimal, all SFT approximations are transitive, thus periodic points are dense in them. The problem with this is that, since \mathcal{G} is not finitely-presented, we do not see a general reason why such periodic orbits should exist. Below, we explain how to get them by an ad hoc argument, by modifying the words w_n we used to define \mathcal{S} .

Write \widehat{w} for the circular version of a word w , where we imagine the left and right ends are glued together. There is a natural analog of the set of SAWs W , \widehat{W} , where the requirements are those of W , but we require them for all rotations of the word (equivalently, the constraint on adjacent letters is extended to the pair formed of the first and last letters), and additionally the star cannot be at the very end of the word, the point being that thinking of the word as circular, this is the same as putting the star in the beginning of the word. Similarly, we can talk about circular AWs and their starrings. We extend the jump action to \widehat{W} in the obvious way.

We claim that \mathcal{G} admits a well-defined action on the starrings of $\widehat{(w_n\alpha)^2} = \widehat{w_n\alpha w_n\alpha}$ where $w_{n+1} = w_n\alpha w_n$. To see this, we think of the action of $H = \mathbb{Z}_2 * \mathbb{Z}_2$ on $\widehat{(w_n\alpha)^2}$ as follows: Letting I be the star positions of w_n (including the last positions; $|I| = 2^n$), we act on $I \times \mathbb{Z}_2$; the action factors onto the natural action on I , and the action on the bit $b \in \mathbb{Z}_2$ is that at each end of I , some of the generators increase b by 1. This description makes sense because w_n is a palindrome, simply imagine that the bit keeps track of which copy of w_n we are in, and imagine that the rightmost copy of w_n is reversed.

Next, we give an alternative description of the jump action on $w_{n+1} = w_n\alpha w_n$. Again we can think of the group as acting on $I \times \mathbb{Z}_2$. The action on I is the exact same, but now we flip the \mathbb{Z}_2 bit if and only if we are at the right end of w_n .

Now suppose that a group element $g \in H$ acts trivially on the starrings of $w_n\alpha w_n$. Then in the $I \times \mathbb{Z}_2$ point of view, if we start at (i, b) or $(2^n - 1 - i, b)$ we in particular flip the bit b an even number of times. Observe that $i \mapsto 2^n - 1 - i$ is an automorphism of the action on the starrings of w_n , again because w_n is a palindrome, so we can interpret the action on pairs $(2^n - 1 - i, b)$ as the action on $I \times \mathbb{Z}_2$ but now the bit b is flipped when we are at the *left* end of I . All in all, the fact we fix (i, b) (resp. $(2^n - 1 - i, b)$) means that on $i \in I$, the action of g flips b on the left (resp. right) an even number of times. In particular, in the first action we described on $I \times \mathbb{Z}_2$ (corresponding to the jump action on $\widehat{w_n\alpha w_n\alpha}$) the bit is flipped an even number of times (because even + even = even).

Note that it immediately follows that \mathcal{G} also has a well-defined action on $\widehat{w_n\alpha}$. Namely, $(H, \widehat{w_n\alpha})$ is a quotient of $(H, \widehat{(w_n\alpha)^2})$ under taking the star position modulo 2^n , and if $g \in H$ acts trivially on $\widehat{(w_n\alpha)^2}$ then in particular it acts trivially when we identify some positions.

Let $X = \{a, B, C, D\}^{\mathbb{Z}}$. Observe that although $x_n = (w_n\alpha)^{\mathbb{Z}} \in X$ is not in \mathcal{S} , \mathcal{G} admits a well-defined action on its shift orbit. Namely, the action of H on this orbit is exactly the same as that on $\widehat{w_n\alpha}$, where we already established \mathcal{G} has a well-defined action.

Observe that x_n is in the 2^n th SFT approximation of \mathcal{S} seen as a \mathbb{Z} -subshift, meaning the words of length 2^n and less are taken from \mathcal{S} . This is clear, as they

all appear in the word w_{n+1} , which in turn appears (syndetically) in all points of \mathcal{S} .

Because the action of \mathcal{G} is well-defined on the orbit $O(x_n) = \{\sigma^k(x) \mid k \in \mathbb{Z}\}$, we can associate to $g \in \mathcal{G}$ the point $g \blacktriangleright_j x_n$, to obtain a map $\phi : \mathcal{G} \rightarrow O(x_n) \subset X$. Since each shift of x_n is in the 2^n th SFT approximation, we can pick for each $\phi(g) = g \blacktriangleright_j x_n$ an approximating point $y_g \in \mathcal{S}$ with $d(y_g, \phi(g)) \leq 2^{-n+1}$ in the Cantor metric of X .

Then because ϕ is an actual orbit, it follows from the triangle inequality of X that $g \mapsto y_g$ is a 2^{-n+3} -pseudo-orbit: for α one of the natural generators, we have

$$\begin{aligned} d(\alpha \blacktriangleright_j y_g, y_{\alpha g}) &\leq d(\alpha \blacktriangleright_j y_g, \alpha \blacktriangleright_j \phi(g)) + d(\alpha \blacktriangleright_j \phi(g), \phi(\alpha g)) + d(\phi(\alpha g), y_{\alpha g}) \\ &\leq 2^{-n+2} + 0 + 2^{-n+1} \\ &\leq 2^{-n+3} \end{aligned}$$

Where we note that the action of α either behaves trivially or shifts the points by ± 1 , which by our choice of metric on Cantor space can at most double distances.

We claim that this pseudo-orbit $(y_g)_{g \in \mathcal{G}}$ is not $1/2$ -traced by any point of \mathcal{S} for sufficiently large n . Namely suppose it were $1/2$ -traced by some z . Then, by the definition of $1/2$ -tracing and the choice of the y_g we would have

$$(g \blacktriangleright_j z)_0 = (y_g)_0 = (g \blacktriangleright_j x_n)_0.$$

The jump action of \mathcal{G} on \mathcal{S} is expansive, and it is easy to see that $1/2$ is an expansivity constant, i.e. we can shift any position of z to the origin. From this we conclude that $z = x_n$. Since $x_n \notin \mathcal{S}$, this is a contradiction. So the system $(\mathcal{G}, \mathcal{S})$ does not have the pseudo-orbit tracing property. \square

As a ‘‘sanity check’’ we checked that the action of the group \mathcal{G} on starrings of $\widehat{(w_n \alpha)^2}$ is indeed well-defined. In fact, we tested, for each $n \in [1, 6]$ and each $p \in [1, 20]$ whether the elements in R_t act as identity in the H -action on starrings of $\widehat{(w_n \alpha)^p}$:

$$R_t = \{a^2, b^2, c^2, d^2, bcd, \kappa^k((ad)^4), \kappa^k((adacac)^4) \mid 1 \leq k \leq t\}$$

Here, κ is the substitution $\kappa(a) = aca, \kappa(b) = d, \kappa(c) = b, \kappa(d) = c$. These are so-called Lysenok relations, and $\bigcup_t R_t$ is a presentation of the group \mathcal{G} .

The table agrees with our result above that there is a well-defined action on starrings of $\widehat{(w_n \alpha)^2}$. This table, and the tables where we checked the same for smaller t , also suggest some other things, which we did not try to prove: the action of the group \mathcal{G} is well-defined on $\widehat{(w_n \alpha)^4}$ and $\widehat{(w_n \alpha)^8}$, but no higher powers. Furthermore, if we check only the relations R_t , then the first t rows of the table look correct (having 1 in slots 1, 2, 4, 8) and the $(t+1)$ th row is all 1, i.e. we are not able to detect a contradiction.

8 The system $(\mathcal{G}, \mathcal{V})$ is a proper sofic shift

We show that the system $(\mathcal{G}, \mathcal{V})$ is also a proper sofic shift. We will deduce this entirely abstractly from our results from $(\mathcal{G}, \mathcal{S})$. The system $(\mathcal{G}, \mathcal{V})$ is

$n \setminus p$	1	2	3	4	5	6	7	8	9	10–50
1	1	1	0	1	0	0	0	1	0	0
2	1	1	0	1	0	0	0	1	0	0
3	1	1	0	1	0	0	0	1	0	0
4	1	1	0	1	0	0	0	1	0	0
5	1	1	0	1	0	0	0	1	0	0
6	1	1	0	1	0	0	0	1	0	0

Table 1: Row n , column p contains 1 if initial Lysenok relations hold for the H -action on $\widehat{w_n\alpha^p}$.

obtained by quotienting the system $(\mathcal{X}, \mathcal{S})$ by the orbit relation of the reversal map $f : \mathcal{S} \rightarrow \mathcal{S}$ defined by $f(x)_i = x_{-1-i}$.

The reversal f gives a free continuous \mathbb{Z}_2 -action on X , and thus the quotient map from X to X/f is exactly 2-to-1, i.e. every point has exactly 2 preimages. It is a general fact that a quotient map by the orbit relation of a continuous finite group action is open. Namely let $Y = X/H$ for a finite group H . If $U \subset X$ is open, then the full ϕ^{-1} -preimage of its ϕ -image is open, because $\phi^{-1}(\phi(U)) = \bigcup_{h \in H} hU$. By the definition of a quotient map, this implies $\phi(U)$ is open.

We start with two basic topological lemmas.

Lemma 26. *Let X, Y be metric spaces and let $\phi : X \rightarrow Y$ be a constant-to-1 open continuous map. Let X be compact. Then there exists $\epsilon' > 0$ such that $\phi(x) = \phi(x')$ and $x \neq x'$ imply $d(x, x') \geq \epsilon'$.*

Proof. Assume ϕ is (exactly) k -to-1. If such $\epsilon' > 0$ did not exist, then we could find $y_i \in Y$ with preimages (exactly) x_i^1, \dots, x_i^k such that $d(x_i^1, x_i^2) < 1/i$ (possibly after reordering). Using compactness of X^k we can take a diagonal limit point of the sequence of k -tuples $(x_i^j)_j$ as $i \rightarrow \infty$ to get preimages (x^1, \dots, x^k) for some y , such that $x^1 = x^2$. Note that $y = \lim_i y_i$ by continuity of ϕ . Since there are at most k distinct preimages in this tuple, we find an additional preimage $x^{k+1} \in X$. Pick a small neighborhood for x^{k+1} whose closure does not contain any of the points x^j with $j \leq k$. By openness of ϕ , for any large enough i , y_i has a preimage in U . For large enough i , these preimages differ from the preimages (x_i^1, \dots, x_i^k) , so y_i has at least $k + 1$ preimages. \square

The following is known in much greater generality, we give a specific proof.

Lemma 27. *Let X, Y be metric spaces and let $\phi : X \rightarrow Y$ be a constant-to-1 open continuous map. Then the map $y \mapsto \phi^{-1}(y)$ is continuous with respect to the Hausdorff metric.*

Proof. Suppose this map were not continuous at some $y \in Y$, and let y have (exactly) preimages x^1, \dots, x^k . By discontinuity at this point, and the definition of the Hausdorff metric, there exists $\epsilon > 0$ such that for each i we find y_i such that $d(y_i, y) < 1/i$ and y_i has (exactly) preimages x_i^1, \dots, x_i^k , so that (possibly after renumbering) x_1 is not in the ϵ -neighborhood of any of the points x_i^j . As in the previous proof, by openness, in a sufficiently small neighborhood of x_1 we can find preimages for y^i for large enough i , so the map is not k -to-1. \square

We next prove two results that show respectively that a nice enough cover preserves the property of being SFT, and a nice enough factor preserves expansivity. (Actually by similar proofs one can show that for such factor maps, the properties are preserved in both directions, i.e. factors preserves the SFT property and covers preserve expansivity.)

For the first result, we do not know if this result is directly in the literature, but for a related result on \mathbb{Z} , we cite [9].

Lemma 28. *Let G be a group generated by a finite set S . Let (G, X) and (G, Y) be group actions on compact metrizable topological spaces X, Y . Suppose $\phi : X \rightarrow Y$ is an open constant-to-1 factor map. If Y has the pseudo-orbit tracing property, then so does X .*

Proof. The idea is simply to map a pseudo-orbit x from X to Y by using the factor map, trace the resulting pseudo-orbit y in Y by an actual orbit of some $y' \in Y$ using the pseudo-orbit tracing property of Y , and then pick a preimage x' of the tracing point that is close to the preimage of $y(1)$ (using the continuity of ϕ^{-1} from the previous lemma). It then follows automatically from the separatedness of the ϕ^{-1} preimages (from Lemma 26) that x' traces x .

We now prove this in detail. Let $\epsilon > 0$. We show that for some $\delta > 0$, X ϵ -traces (δ, S) -pseudo-orbits.

Assume that the set of ϕ -preimages of any $y \in Y$ is $\epsilon' > 0$ separated pairwise (using Lemma 26). We may assume ϵ is small (since if $x \in X$ ϵ -traces a pseudo-orbit, it also γ -traces it for any $\gamma > \epsilon$). In particular, we may assume ϵ is small enough that $d(x, x') < \epsilon$ implies $d(sx, sx') < \epsilon'/3$ for all $s \in S \cup \{1\}$.

Let now $\epsilon_0 > 0$ be such that if $y, y' \in Y$ and $d(y, y') < \epsilon_0$, then we have $d(\phi^{-1}(y), \phi^{-1}(y')) < \epsilon$ in Hausdorff metric (which exists by Lemma 27). Let $\delta_0 > 0$ be such that Y ϵ_0 -traces (δ_0, S) -pseudo-orbits. Let $\delta > 0$ be such that $d(x, x') < \delta \implies d(\phi(x), \phi(x')) < \delta_0$ for $x, x' \in X$. We may assume also $\delta < \epsilon'/3$.

Now let $x : G \rightarrow X$ be a (δ, S) -pseudo-orbit. Define $y : G \rightarrow Y$ by $y(g) = \phi(x(g))$. Then $d(sy(g), y(sg)) = d(s\phi(x(g)), \phi(x(sg))) = d(\phi(sx(g)), \phi(x(sg))) < \delta_0$ for all $s \in S$, by the choice of δ and the fact x is a pseudo-orbit. Then there is an actual orbit of some $y' \in Y$ that ϵ_0 -traces y , i.e. $d(gy', y(g)) < \epsilon_0$ for all $g \in G$.

Since $d(y(1), y') < \epsilon_0$, we have $d(\phi^{-1}(y(1)), \phi^{-1}(y')) < \epsilon$ in Hausdorff metric, and thus we can pick $x' \in \phi^{-1}(y')$ so that $d(x(1), x') < \epsilon$. We prove by induction that for all r , $d(gx', x(g)) < \epsilon$ for all $g \in B_r$ (where B_r is the ball of radius r with respect to generators S). This is true for $r = 0$ by the choice of x' . Now suppose it is true for $g \in S^r$, and consider $s \in S$.

We have $d(sgy', y(sg)) < \epsilon_0$. The points $sgy', y(sg)$ have at least the preimages $sgx', x(sg)$ respectively. By the inductive assumption $d(gx', x(g)) < \epsilon$, from which $d(sgx', sx(g)) < \epsilon'/3$ by the choice of ϵ , and then

$$d(sgx', x(sg)) \leq d(sgx', sx(g)) + d(sx(g), x(sg)) < 2\epsilon'/3$$

since $d(sx(g), x(sg)) < \delta < \epsilon'/3$ (since x is a (δ, S) -pseudo-orbit).

Since $d(\phi^{-1}(y(sg)), \phi^{-1}(sgy')) < \epsilon$ in Hausdorff metric (again by the relation of ϵ_0 and ϵ), there is a ϕ -preimage z for $y(sg)$ at distance less than ϵ from the point $sgx' \in \phi^{-1}(sgy')$. We claim that this preimage must be $z = x(sg)$. If not,

then we have

$$0 < d(z, x(sg)) \leq d(z, sgx') + d(sgx', x(sg)) < \epsilon + 2\epsilon'/3 < \epsilon'$$

contradicting the assumption that $\phi^{-1}(y(sg))$ is ϵ' -separated.

This shows that $d(x(sg), sgx') < \epsilon$, concluding the inductive step since sg enumerates B_{r+1} as we range over $g \in B_r, s \in S$. Since $\bigcup_r B^r = G$, this shows $d(gx', x(g)) < \epsilon$ for all $g \in G$, so indeed x' ϵ -shadows x , finishing the proof. \square

Lemma 29. *Let G be a group generated by a finite set S . Let (G, X) and (G, Y) be group actions on compact metrizable topological spaces X, Y . Suppose $\phi : X \rightarrow Y$ is an open constant-to-1 factor map. If X is expansive, then so is Y .*

Proof. By Lemma 26, there exists $\epsilon' > 0$ such that for any $y \in Y$, $\phi^{-1}(y)$ is pairwise ϵ' -separated. Let $\epsilon > 0$ be an expansivity constant for X . We may assume ϵ is small enough that $d(x, x') < \epsilon$ implies $d(sx, sx') < \epsilon'/2$ for all $s \in S \cup \{1\}$.

Using Lemma 27, pick $\delta > 0$ such that $d(y, y') < \delta \implies d(\phi^{-1}(y), \phi^{-1}(y')) < \epsilon$. We claim that δ is an expansivity constant. Suppose that it is not. Then we can find $y, y' \in Y$ distinct, such that $d(gy, gy') < \delta$ for all $g \in G$. Then we have $d(\phi^{-1}(gy), \phi^{-1}(gy')) < \epsilon$ for all $g \in G$ by the choice of δ .

Pick $x \in \phi^{-1}(y), x' \in \phi^{-1}(y')$ with $d(x, x') < \epsilon$. Analogously to the previous proof, we prove by induction on r that $d(gx, gx') < \epsilon$ for all $g \in B_r$.

If $d(gx, gx') < \epsilon$ then $d(sgx, sgx') < \epsilon'/2$. We need to show that actually $d(sgx, sgx') < \epsilon$. Since $d(sgy, sgy') < \delta$, we have $d(\phi^{-1}(sgy), \phi^{-1}(sgy')) < \epsilon$, so there is a ϕ -preimage z of sgy' at distance less than ϵ from sgx . This must be precisely sgx' , since

$$d(z, sgx') \leq d(z, sgx) + d(sgx, sgx') < \epsilon + \epsilon'/2 < \epsilon'$$

and $\phi^{-1}(sgy')$ is ϵ' -separated. \square

Theorem 5. *The system $(\mathcal{G}, \mathcal{V})$ is topologically conjugate to a proper sofic shift on the group \mathcal{G} .*

Proof. Since the system $(\mathcal{G}, \mathcal{V})$ is a factor of $(\mathcal{G}, \mathcal{S})$, and $(\mathcal{G}, \mathcal{S})$ is sofic, $(\mathcal{G}, \mathcal{V})$ is also SFT covered.

We now show that $(\mathcal{G}, \mathcal{V})$ is a subshift. The space of marked Schreier graphs for any group is a compact zero-dimensional and metrizable space, so it suffices to prove expansivity. This is the content of the previous lemma.

Since $(\mathcal{G}, \mathcal{V})$ is an open exactly 2-to-1 factor of $(\mathcal{G}, \mathcal{S})$, and $(\mathcal{G}, \mathcal{S})$ is not an SFT, $(\mathcal{G}, \mathcal{V})$ cannot be pseudo-orbit tracing by the Lemma 28, thus it is not an SFT. In other words, $(\mathcal{G}, \mathcal{V})$ is proper sofic. \square

Remark 6. *As mentioned above, lemmas 28 and 29 prove only one direction of an if and only if condition. By proving the other ones, we could have equivalently concentrated on the system $(\mathcal{G}, \mathcal{V})$ in this paper, and abstractly deduced the properties of the system $(\mathcal{G}, \mathcal{S})$.*

9 The system $(\mathcal{G}, \mathcal{T})$ is pseudo-orbit tracing

The system $(\mathcal{G}, \mathcal{T})$ is also not SFT, for the trivial reason that it is not expansive, so not a subshift in the first place. As we explained in Section 2, among subshifts SFTs are characterized by the pseudo-orbit tracing property. Perhaps surprisingly (in this light), for very general reasons, $(\mathcal{G}, \mathcal{T})$ does have the pseudo-orbit tracing property.

Lemma 30. *Let X be a compact metrizable zero-dimensional space, let G be a finitely-generated group acting on X equicontinuously. Then (G, X) has the pseudo-orbit tracing property.*

Proof. We may assume $X \subset \{0, 1\}^{\mathbb{N}}$ is a closed set. Let $m \in \mathbb{N}$. In terms of coordinates, equicontinuity means that there exists $n \in \mathbb{N}$ such that for $x \in X$, the word $x|_{[0, n-1]}$ determines the G -tuple $T(x) = ((g \blacktriangleright x)|_{[0, m-1]})_{g \in G}$ uniquely. A direct calculation shows that these G -tuples form a G -subshift Y over alphabet $\{0, 1\}^m$, and that the map from x to $T(x)$ is a surjective factor map from X to Y as G -systems. The subshift Y is finite, as we showed it has at most $\{0, 1\}^n$ points.

A finite factor for (G, X) is equivalent to a finite partition of X into clopen sets C_1, \dots, C_k , such that the action of G respects the partition in the sense that for all i , there exists j such that $g \blacktriangleright C_i = C_j$. Furthermore, from the construction is it clear that the diameters of the C_i can be made arbitrarily small – the diameters of the C_i are at most those of the cylinders $[x|_{[0, m-1]}]$.

Let $\epsilon > 0$ be arbitrary and construct an invariant clopen partition $(C_i)_{i=1}^k$ with each C_i having diameter at most ϵ . Since the sets C_i are compact, we can find $\delta > 0$ with $\delta < \epsilon$ such that if $d(x, y) < \delta$ and $x \in C_i$, then $y \in C_i$ as well. For $x \in X$, write $C(x) = i$ for the unique i such that $x \in C_i$.

Let now F be any finite generating set for G and let $z : G \rightarrow X$ be a (δ, F) -pseudo-orbit. Let $x = z(1_G)$. We prove by induction on r that for $g \in B_r$ (the ball of radius r in G with generators F) we have $C(z(g)) = C(gx)$, from which we then conclude $d(z(g), gx) < \epsilon$ for all $g \in G$, proving the pseudo-orbit tracing property.

For this, suppose the claim is true for $g \in B_r$ and consider any $s \in F$. Then by the assumption that the partition $(C_i)_i$ is respected by G , we have that $C(z(g)) = C(gx)$ implies $C(sz(g)) = C(sgx)$. By the assumption that z is a pseudo-orbit, we have $d(sz(g), z(sg)) < \delta$, so by the choice of δ also $C(z(sg)) = C(sz(g)) = C(sgx)$, which concludes the proof since sg gives all elements of B_{r+1} . \square

Proposition 2. *The system $(\mathcal{G}, \mathcal{T})$ has the pseudo-orbit tracing property.*

Proof. This system satisfies the assumptions of the previous lemma. \square

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